### CSE 3221.3 Operating System Fundamentals

**No.8** 

# **Memory Management (1)**

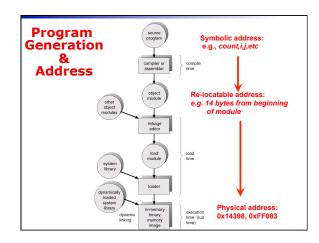
Prof. Hui Jiang
Dept of Computer Science and Engineering
York University

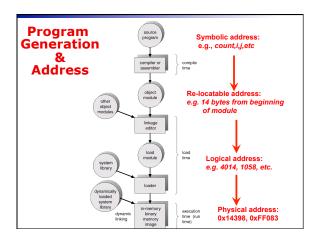
# **Memory Management**

- A program usually resides on a disc as a binary executable file.
- The program can be moved between disk and memory.
- Program must be brought into memory and placed within a process for it to be executed.
- In multiprogramming, we keep several programs in memory.
- · Memory management algorithms:
  - Contiguous Memory Allocation
  - Paging
  - Segmentation
  - Segmentation with paging
- Memory management needs hardware support MMU.

### **Background**

- Physical memory consists of a large array of words or bytes, each with its own address.
- In a typical instruction-execution cycle:
  - CPU fetches an instruction from memory according to PC .
  - The instruction is decoded.
  - CPU may fetch operands from memory according to the address in the instruction. (optional)
  - CPU execute in registers
  - CPU saves results into a memory address (optional)
- CPU generates address from program counter, program address,etc.
- CPU sends the address to a memory management unit (MMU), which is hardware to actually locate the memory at certain location.
- Memory mapping (address translation).
- Memory protection.





# **Using Logical Memory Space**

Address binding: binding the logical memory addresses in instructions and data to physical memory addresses.

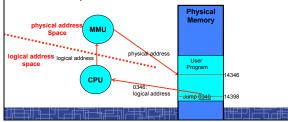
- In source programs: symbolic addresses (e.g., count, i, j, etc.)
- A compiler will bind each symbolic address to a relocatable address (e.g. 14 bytes from the beginning of the module)
- The linkage editor or loader will bind each relocatable address to a logical address (e.g., 4014)
- In run-time, MMU will bind each logical address to a physical address (e.g., 074014)
- The final physical address is used to locate memory.

Allow a user program to be loaded in any part of the physical memory → address binding in run-time

→ completely separate physical address from logical address

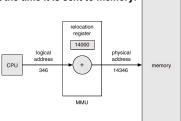
# **Logical vs. Physical Address**

- Physical address: the address loaded into the memoryaddress register to actually address the memory.
- Logical (virtual) address: an address generated by the CPU and the address referred by user program; address used in binary codes.



# **Memory-Management Unit (MMU)**

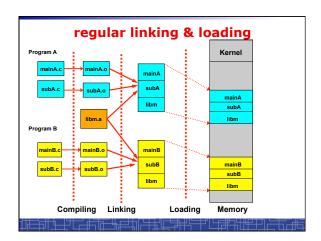
- MMU: maps logical address to physical address.
- The user program deals with logical addresses; it never sees the real physical addresses.
- A simple MMU scheme, the value in the relocation register is added to every address generated by a user process at the time it is sent to memory.



# Logical vs. Physical address (2)

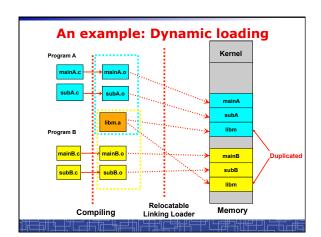
- Separating logical address from physical address:
  - Requires hardware support MMI does address mapping dynamically.
- Why separating logical address from physical address?
  - Easier for compiler
  - More benefits to OS memory management
  - Consider two old methods ...

# **Address Binding: compile-time** In compiling, physical address is generated for every instruction. The compiler has to know where the process will reside The code can not change location in memory unless it is No separation of logical and physical address spaces. Example: .COM format in MS-DOS. - Not a choice for a multiprogramming system. **Address Binding: load-time** The compiler generate re-locatable code. When OS loading code to memory, physical address is generated for every instruction in the program. The process can be loaded into different memory locations. But once loaded, it can not move during execution. Loading a program is slow. Benefits to separate LA from PA Easier for compiler: - Generate binary codes in separate logical spaces. - All instructions use LA. Maximum flexibility for OS to manage memory: - Program loading is fast, just direct copy. - The same binary code can be loaded anywhere in memory. - A loaded program can be re-located in memory. Need hardware MMU support.



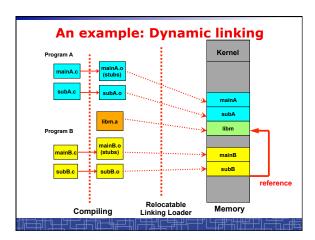
# **Dynamical Loading**

- Routine is not loaded until it is called.
- Better memory-space utilization; unused routine is never loaded.
- Useful when large amounts of code are needed to handle infrequently occurring cases.
- No special support from the operating system is required; Implemented through program design.
- Each program maintains an address table to indicate which module is in memory and which is not.



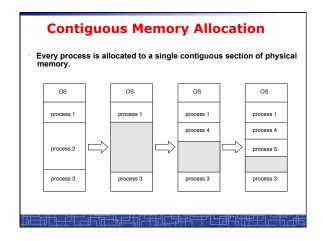
# **Dynamical Linking**

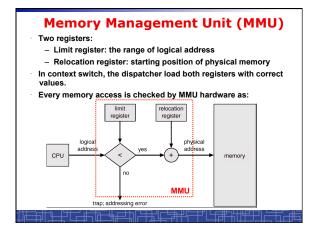
- Linking postponed until execution time.
- In dynamic linking, a *stub,* is included in the executable image for each library-routine reference.
- Stub: used to locate the appropriate memory-resident library routine or load the library of it is not in memory.
- Stub replaces itself with the address of the routine, and executes the routine.
- Operating system needed to check if the routine is in other processes' memory address, and allow multiple processes to access the same memory space
- Dynamical linking is useful for shared libraries.



# **Memory Management Approaches**

- Contiguous Memory Allocation
- Paging
- Segmentation
- Segmentation with paging





# Free Memory Management OS must keep the information on which parts of memory are available and which are occupied. - allocated partitions - free partitions (holes) Hole: a block of free memory. - holes of various size are scattered throughout memory When a process arrives, it is allocated memory from a hole large enough to accommodate it. Use linked lists: | Start | Start | Start | Start | Size | Size | Size | Size | Next | Next | Next | Size | Next | N

# **Dynamic Storage-Allocation Problem**

How to satisfy a request of size n from a list of free holes that have various size.

- · First-fit: Allocate the first hole that is big enough.
- **Best-fit:** Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size. Produces the smallest leftover hole.
- **Worst-fit:** Allocate the *largest* hole; must also search entire list. Produces the largest leftover hole.
- First-fit and best-fit are better than worst-fit in terms of speed and memory utilization.
- 2. First-fit is faster than best-fit.

## Contiguous Memory Allocation: External Fragmentation

- · External fragmentation total memory space exists to satisfy a request, but it is not contiguous.
- · Contiguous memory allocation suffers serious external fragmentation; Free memory is quickly broken into little pieces.
  - 50-percent rule for first fit (1/3 is wasted).
- Reduce external fragmentation by compaction:
  - Shuffle memory contents to place all free memory together in one large block.
  - Compaction is possible only if relocation is dynamic, and is done at execution time.
  - Compaction is very costly.
- Reduce external fragmentation by better memory management methods:
  - Paging.
  - Segmentation.

# Contiguous Memory Allocation: Expanding memory

- · How to allocate more memory to an existing process?
  - Move-and-Copy may be needed.
- It is difficult to share memory among different processes.

(	_	)	
2	×	۱	