

Chapter 4: outline

- 4.1 introduction
- 4.2 virtual circuit and datagram networks
- 4.3 what's inside a router
- 4.4 IP: Internet Protocol
 - datagram format
 - IPv4 addressing
 - ICMP
 - IPv6
- 4.5 routing algorithms
 - link state
 - distance vector
 - hierarchical routing
- 4.6 routing in the Internet
 - RIP
 - OSPF
 - BGP
- 4.7 broadcast and multicast routing

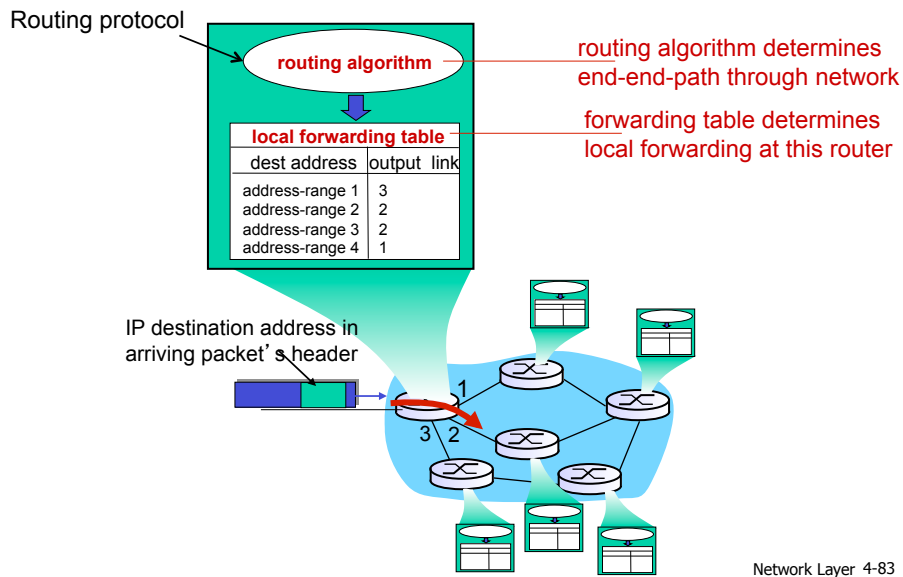
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Routing

- ❖ Routing in the Internet – combination of rules and procedures that allow router to:
 - Inform one another of “status of” or “changes” in the network Routing protocol
 - Determine “best” routing paths in the network Routing algorithm
 - Transfer packets from a source host to a destination host along the best path Packet forwarding
- ❖ Internet Routing Goals: accurate, rapid, low cost delivery of packets
 - Route packets away from failed and temporarily congested nodes or links
 - Avoid routing loops
 - Adapt to varying traffic loads
 - Low overhead

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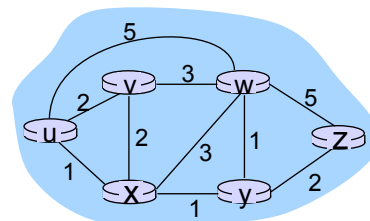
Interplay between routing, forwarding



Routing Algorithm

❖ Routing Algorithm – heart of routing protocol, determines the best path between any two hosts in the network

- **Best path** = path that minimizes the *objective function* that the network operator tries to optimize
- Possible *objective functions*:
 1. Number of hops
 2. End-to-end delay
 3. ISP cost, ...



Network Layer 4-84

Routing algorithm classification

Q: global or decentralized information?

global:

- ❖ all routers have complete topology, link cost info
- ❖ “link state” algorithms

decentralized:

- ❖ router knows physically-connected neighbors, link costs to neighbors
- ❖ iterative process of computation, exchange of info with neighbors
- ❖ “distance vector” algorithms

Q: static or dynamic?

static:

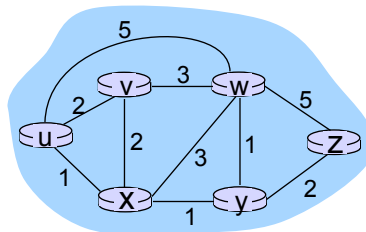
- ❖ routes change slowly over time

dynamic:

- ❖ routes change more quickly
 - periodic update
 - in response to link cost changes

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Graph abstraction



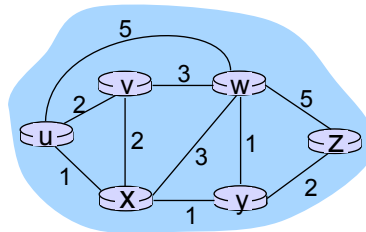
graph: $G = (N, E)$

N = set of routers = $\{ u, v, w, x, y, z \}$

E = set of links = $\{ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) \}$

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Graph abstraction: costs



$c(x, x') = \text{cost of link } (x, x')$
e.g., $c(w, z) = 5$

$c(x, x) = 0$
 $c(x, y) \geq 0$ if nodes directly connected
Cost could be associated with bandwidth and/or congestion

cost of path $(x_1, x_2, x_3, \dots, x_p) = c(x_1, x_2) + c(x_2, x_3) + \dots + c(x_{p-1}, x_p)$

key question: what is the least-cost path between u and z ?
routing algorithm: algorithm that finds that least cost path

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A Link-State Routing Algorithm

Dijkstra's algorithm

- ❖ net topology, link costs known to all nodes
 - accomplished via "link state broadcast"
 - all nodes have same info
- ❖ computes least cost paths from one node ("source") to all other nodes
 - gives *forwarding table* for that node
- ❖ iterative: after k iterations, know least cost path to k destinations

notation:

- ❖ $c(x,y)$: link cost from node x to y; $= \infty$ if not direct neighbors
- ❖ $D(v)$: current value of cost of path from source to v
- ❖ $p(v)$: predecessor node along path from source to v
- ❖ N' : set of nodes whose least cost path definitively known

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Dijkstra's Algorithm

1 **Initialization:**

- 2 $N' = \{u\}$
- 3 for all nodes v
- 4 if v adjacent to u
- 5 then $D(v) = c(u,v)$
- 6 else $D(v) = \infty$
- 7

8 **Loop**

- 9 find w not in N' such that $D(w)$ is a minimum
- 10 add w to N'
- 11 update $D(v)$ for all v adjacent to w and not in N' :
- 12 **$D(v) = \min(D(v), D(w) + c(w,v))$**
- 13 /* new cost to v is either old cost to v or known
- 14 shortest path cost to w plus cost from w to v */
- 15 **until all nodes in N'**

notation:

- ❖ $c(x,y)$: link cost from node x to y; cost = ∞ if not direct neighbors
- ❖ $D(v)$: current value of cost of path from source to v
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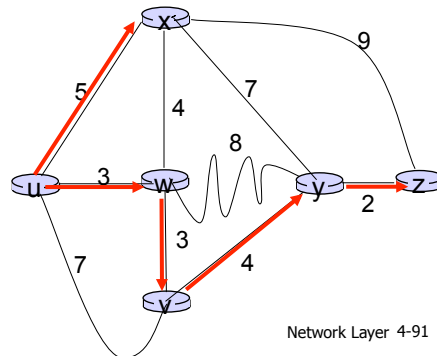
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Dijkstra's algorithm: example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uw x	6,w			11,w	14,x
3	uw x v				10,v	14,x
4	uw x v y					12,y
5	uw x v y z					

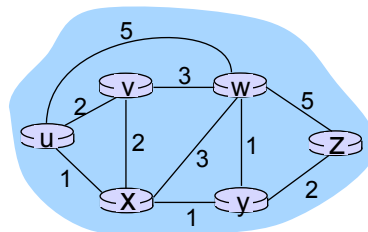
notes:

- ❖ construct shortest path tree by tracing predecessor nodes
- ❖ ties can exist (can be broken arbitrarily)



Dijkstra's algorithm: another example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	ux y	2,u	3,y			4,y
3	ux y v		3,y			4,y
4	ux y v w					4,y
5	ux y v w z					

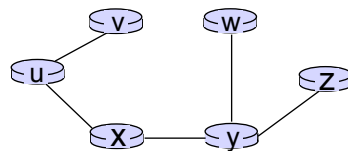


destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

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Dijkstra's algorithm: example (2)

resulting shortest-path tree from u:



resulting forwarding table in u:

destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

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Distance vector algorithm

Bellman-Ford equation (dynamic programming)

let

$d_x(y) :=$ least-cost path from x to y

then

$$d_x(y) = \min_v \{ c(x,v) + d_v(y) \}$$

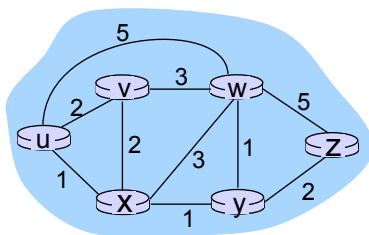
cost from neighbor v to destination y

cost to neighbor v

\min taken over all neighbors v of x

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Bellman-Ford example



clearly, $d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$\begin{aligned} d_u(z) &= \min \{ c(u,v) + d_v(z), \\ &\quad c(u,x) + d_x(z), \\ &\quad c(u,w) + d_w(z) \} \\ &= \min \{ 2 + 5, \\ &\quad 1 + 3, \\ &\quad 5 + 3 \} = 4 \end{aligned}$$

node achieving minimum is next
hop in shortest path, used in forwarding table

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Distance vector algorithm

- ❖ $D_x(y)$ = estimate of least cost from x to y
 - x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- ❖ node x:
 - knows cost to each neighbor v: $c(x,v)$
 - maintains its neighbors' distance vectors. For each neighbor v, x maintains $\mathbf{D}_v = [D_v(y): y \in N]$

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Distance vector algorithm

key idea:

- ❖ from time-to-time, each node sends its own distance vector estimate to neighbors
- ❖ when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:
$$D_x(y) \leftarrow \min_v \{c(x,v) + D_v(y)\} \text{ for each node } y \in N$$
- ❖ under minor, natural conditions, the estimate $D_x(y)$ converge to the actual least cost $d_x(y)$

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Distance vector algorithm

iterative, asynchronous:

each local iteration caused by:

- ❖ local link cost change
- ❖ DV update message from neighbor

distributed:

- ❖ each node notifies neighbors *only* when its DV changes
 - neighbors then notify their neighbors if necessary

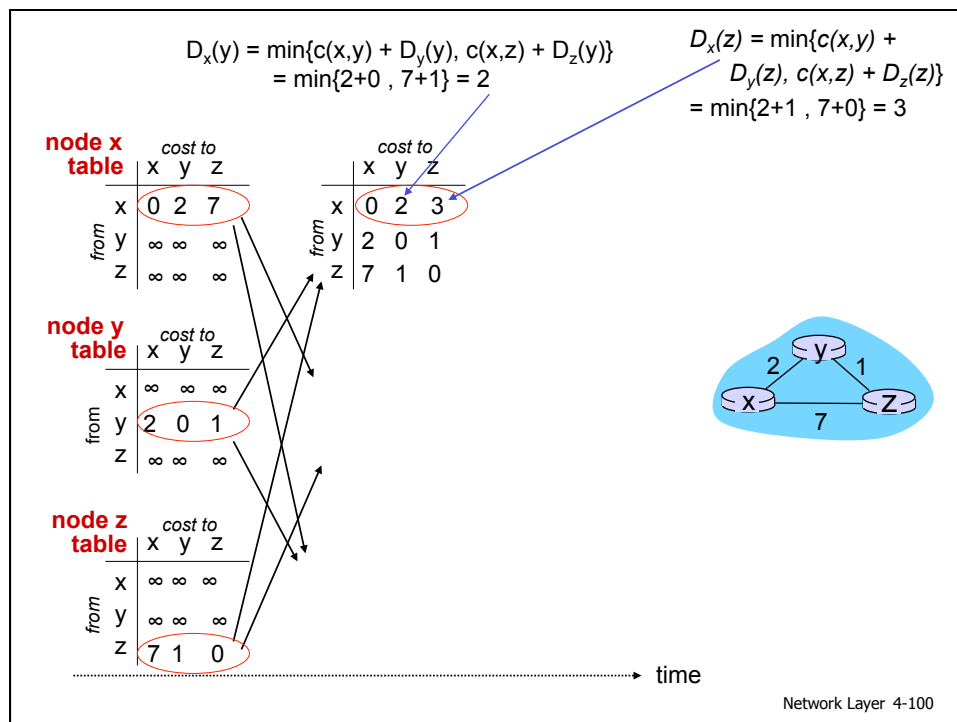
each node:

wait for (change in local link cost or msg from neighbor)

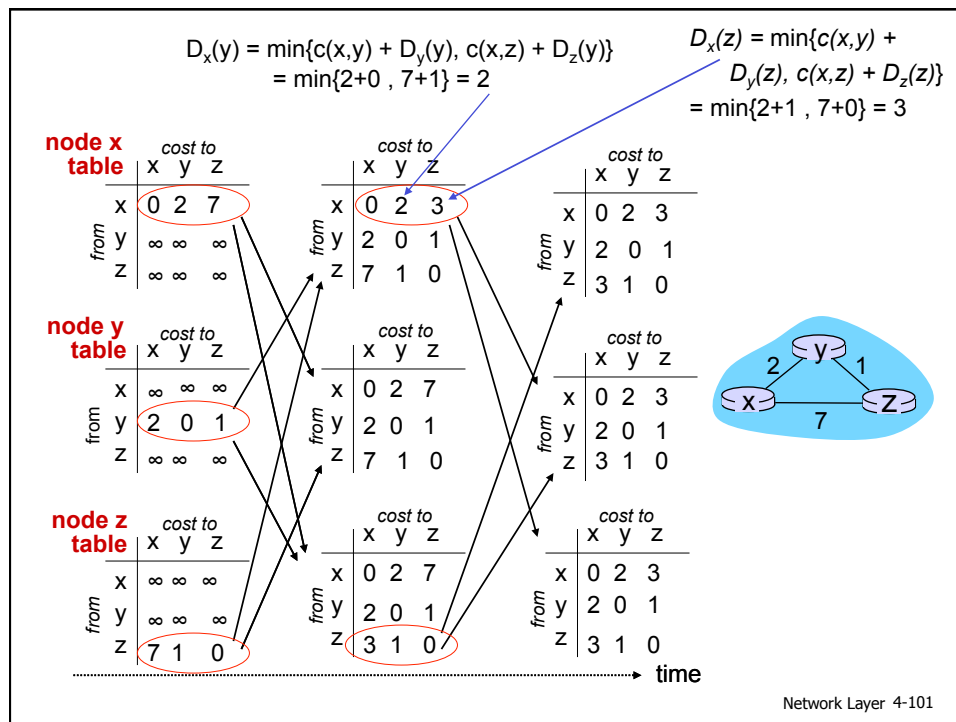
recompute estimates

if DV to any dest has changed, *notify* neighbors

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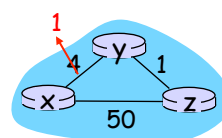
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Distance vector: link cost changes

link cost changes:

- ❖ node detects local link cost change
- ❖ updates routing info, recalculates distance vector
- ❖ if DV changes, notify neighbors



“good news travels fast”

t_0 : y detects link-cost change, updates its DV, informs its neighbors.

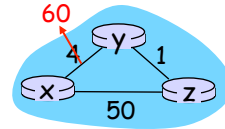
t_1 : z receives update from y, updates its table, computes new least cost to x, sends its neighbors its DV.

t_2 : y receives z's update, updates its distance table. y's least costs do *not* change, so y does *not* send a message to z.

Distance vector: link cost changes

link cost changes:

- ❖ node detects local link cost change
- ❖ *bad news travels slow* - “count to infinity” problem!
- ❖ 44 iterations before algorithm stabilizes: see text



poisoned reverse:

- ❖ If Z routes through Y to get to X :
 - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- ❖ will this completely solve count to infinity problem?

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Comparison of LS and DV algorithms

message complexity

- ❖ **LS:** with n nodes, E links, $O(nE)$ msgs sent
- ❖ **DV:** exchange between neighbors only
 - convergence time varies

speed of convergence

- ❖ **LS:** $O(n^2)$ algorithm requires $O(nE)$ msgs
 - may have oscillations
- ❖ **DV:** convergence time varies
 - may be routing loops
 - count-to-infinity problem

robustness: what happens if router malfunctions?

LS:

- node can advertise incorrect *link* cost
- each node computes only its own table

DV:

- DV node can advertise incorrect *path* cost
- each node's table used by others
 - error propagate thru network

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