| CSE 2021 Computer Organization

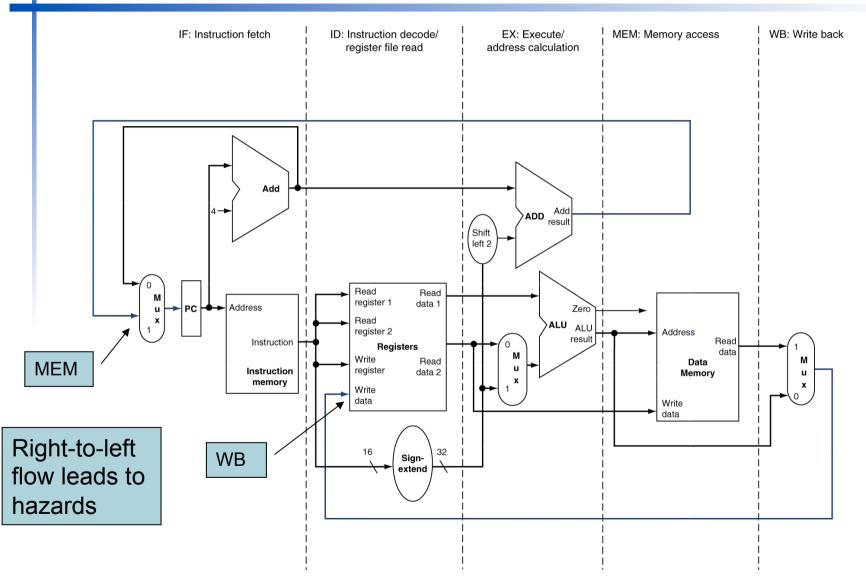
Chapter 4 Part 3

The Processor - Pipelining

Pipeline Summary

- Pipelining improves performance by increasing instruction throughput
 - Executes multiple instructions in parallel
 - Each instruction has the same latency
- Subject to hazards
 - Structure, data, control
- Instruction set design affects complexity of pipeline implementation

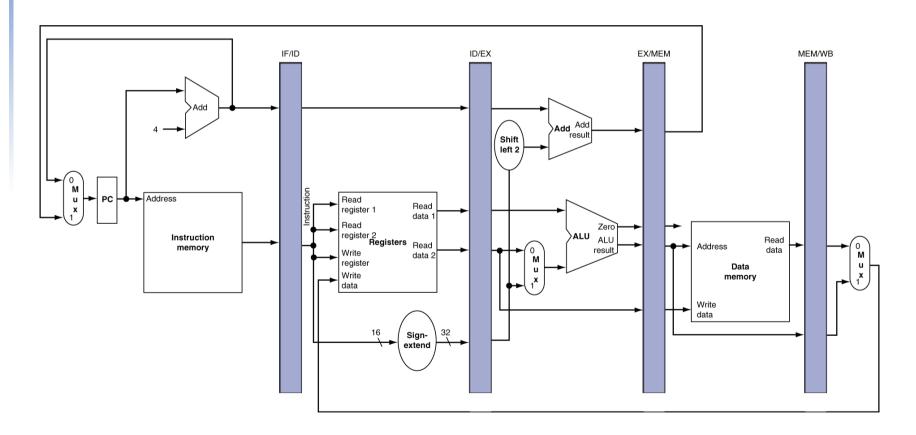
MIPS Pipelined Datapath



Chapter 4 — The Processor — 3

Pipeline registers

- Need registers between stages
 - To hold information produced in previous cycle

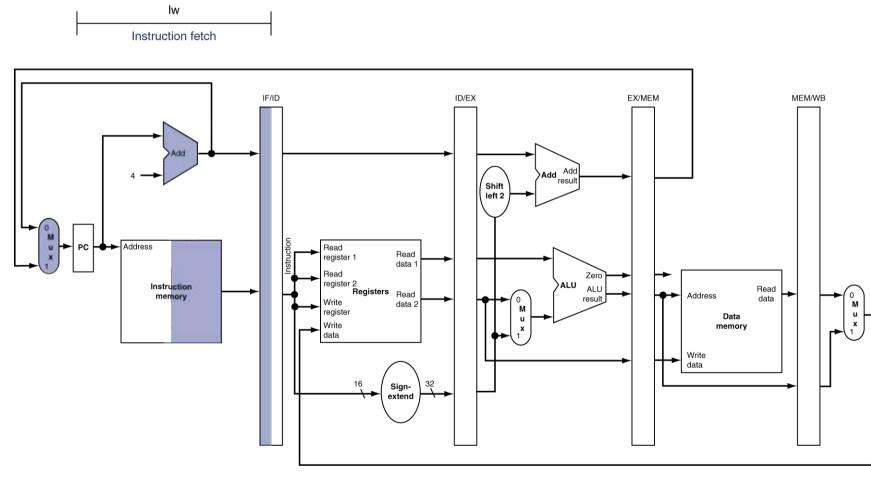


Pipeline Operation

- Cycle-by-cycle flow of instructions through the pipelined datapath
 - "Single-clock-cycle" pipeline diagram
 - Shows pipeline usage in a single cycle
 - Highlight resources used
 - c.f. "multi-clock-cycle" diagram
 - Graph of operation over time
- We'll look at "single-clock-cycle" diagrams for load & store

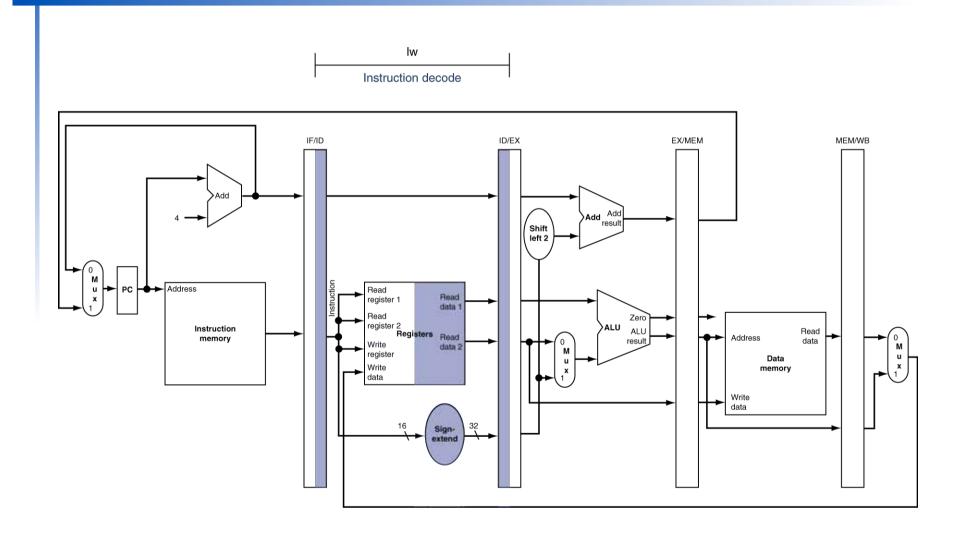
Single-Clock-Cycle Diagram

IF for Load and Store

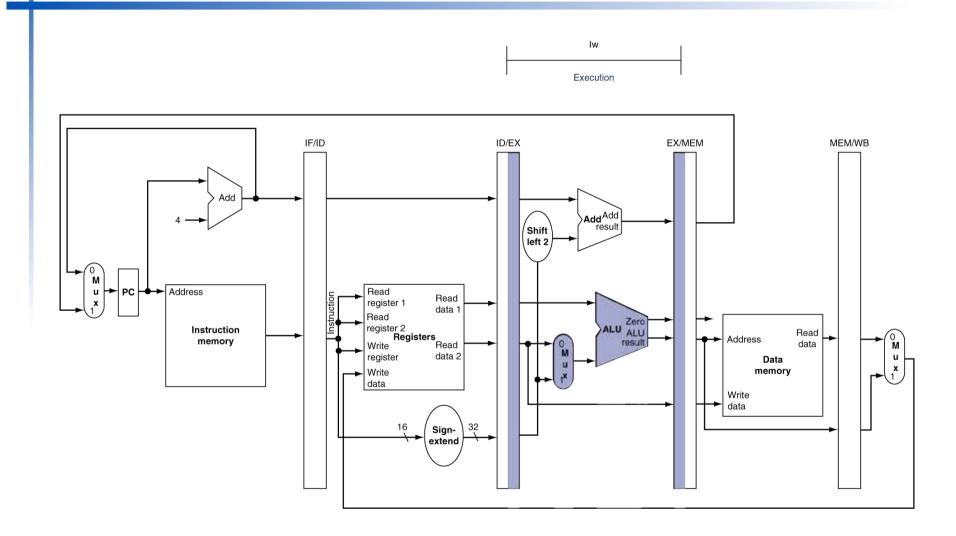


Chapter 4 — The Processor — 6

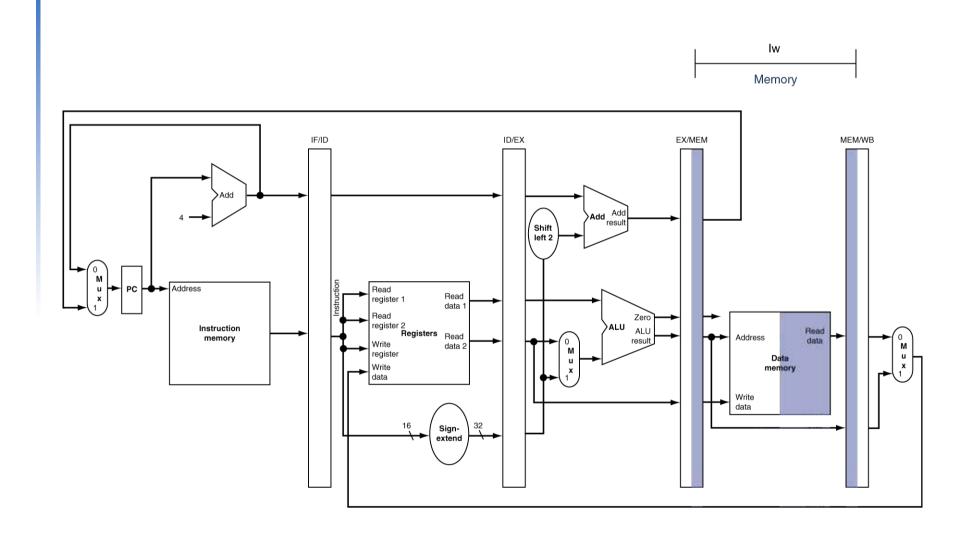
ID for Load, Store, ...



EX for Load

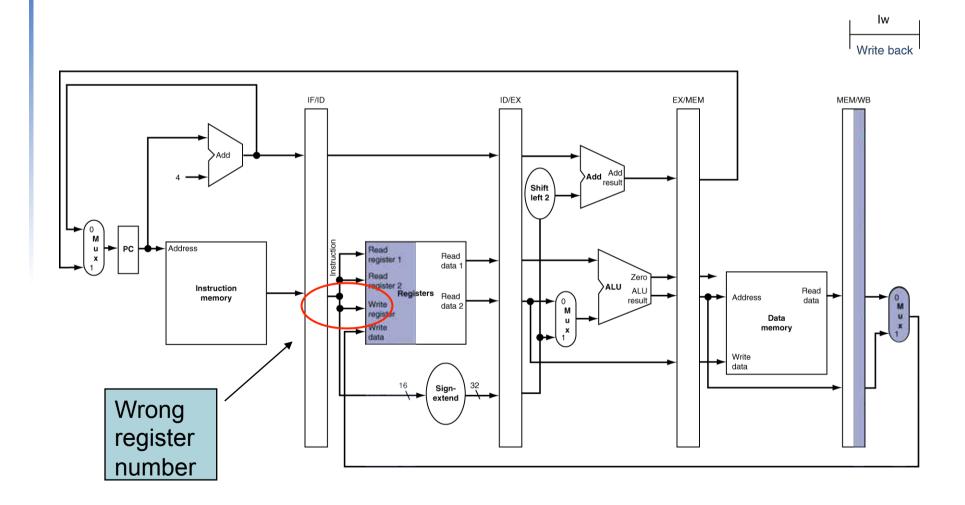


MEM for Load



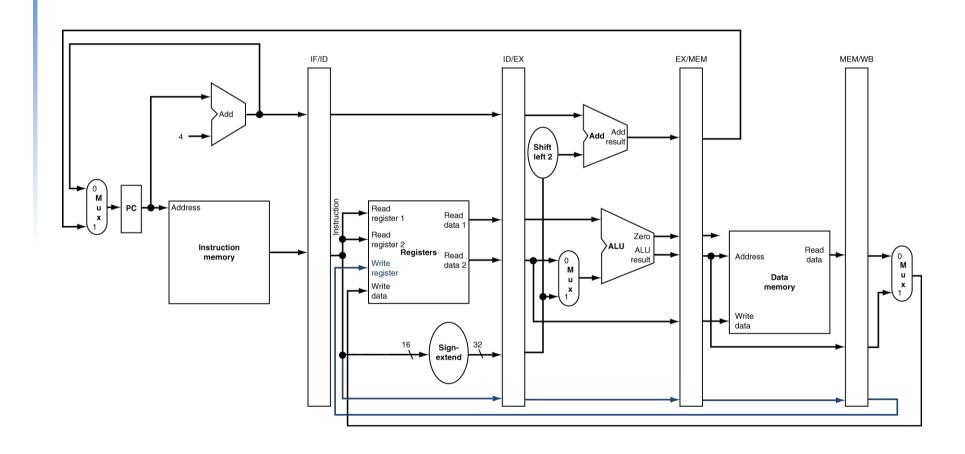
Chapter 4 — The Processor — 9

WB for Load

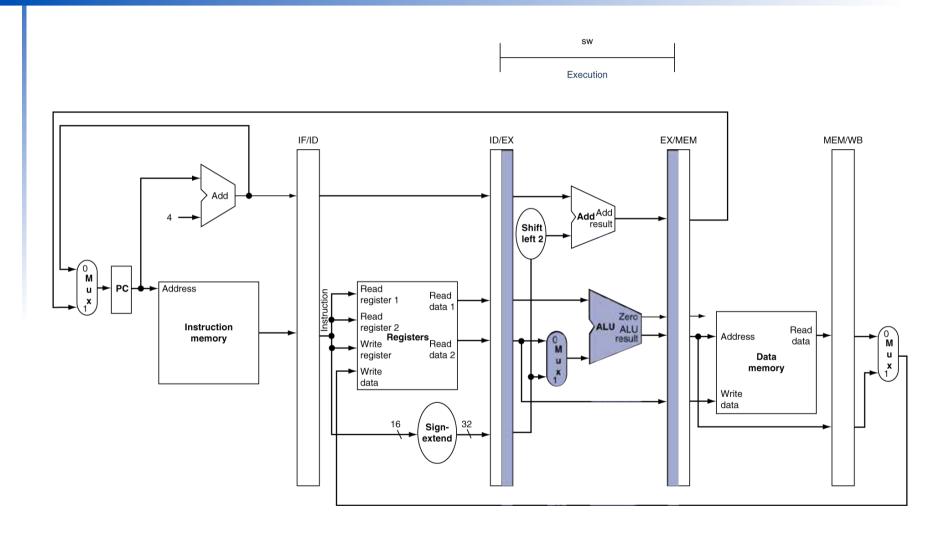


Chapter 4 — The Processor — 10

Corrected Datapath for Load

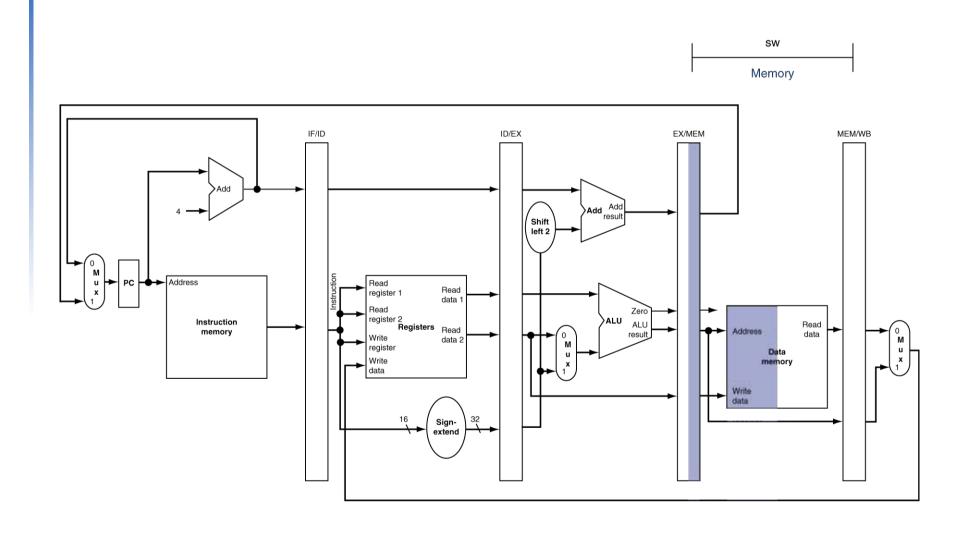


EX for Store



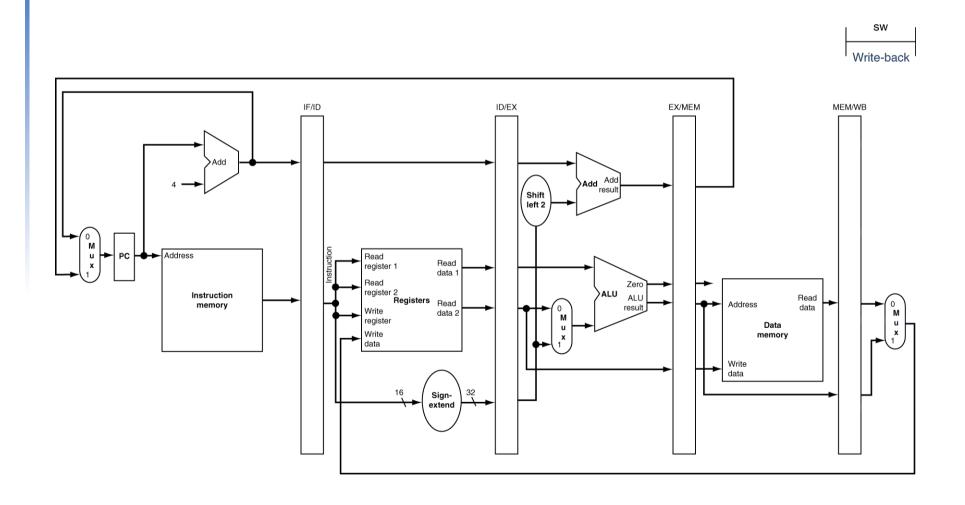
Chapter 4 — The Processor — 12

MEM for Store



Chapter 4 — The Processor — 13

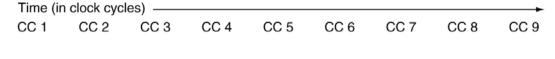
WB for Store

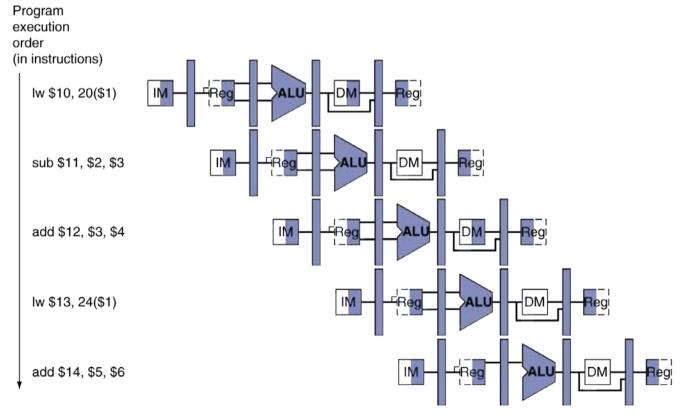


Chapter 4 — The Processor — 14

Multi-Cycle Pipeline Diagram

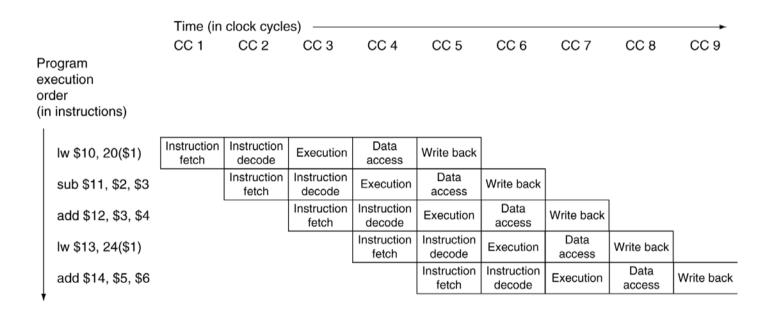
Form showing resource usage





Multi-Cycle Pipeline Diagram

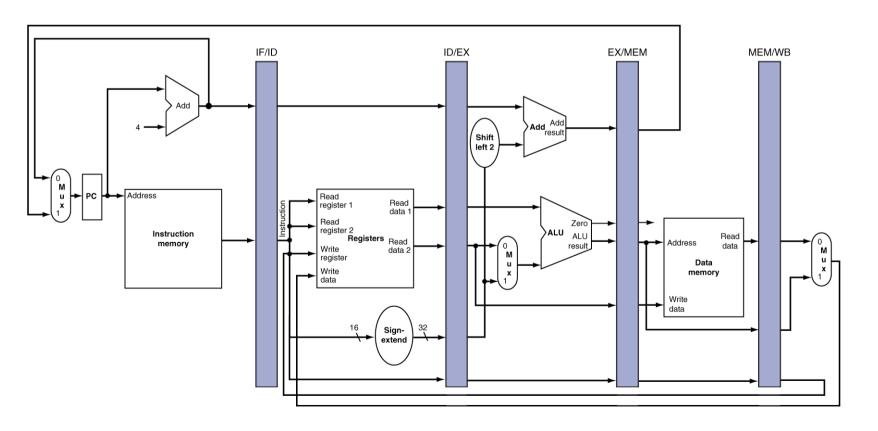
Traditional form



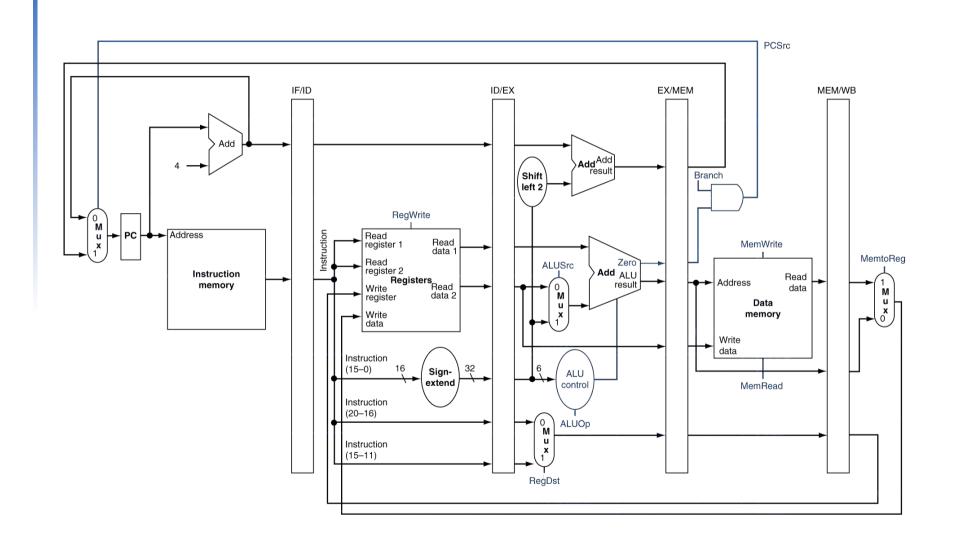
Single-Cycle Pipeline Diagram

State of pipeline in a given cycle



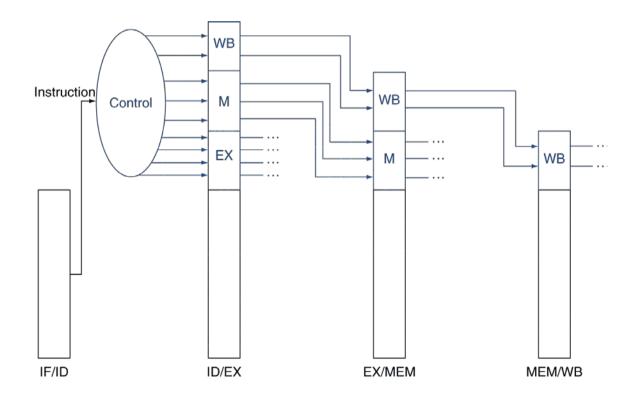


Pipelined Control (Simplified)

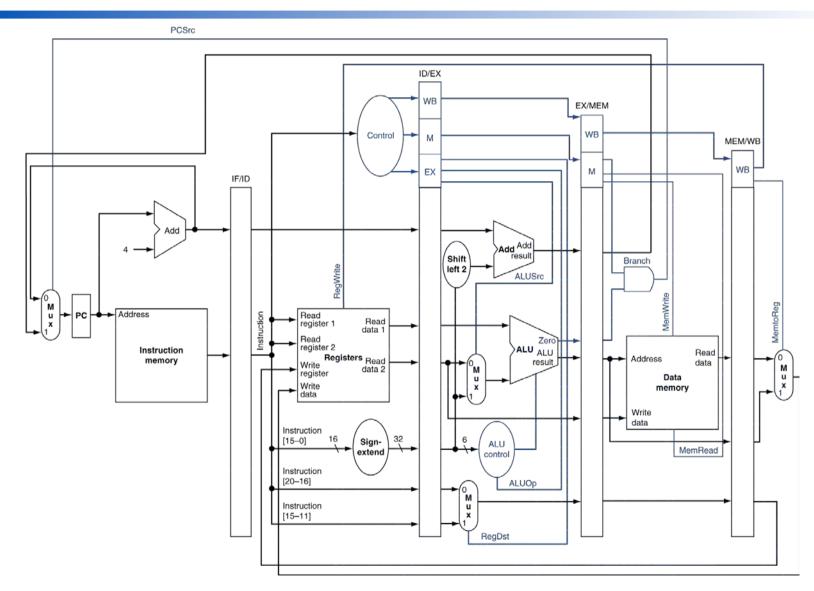


Pipelined Control

- Control signals derived from instruction
 - As in single-cycle implementation



Pipelined Control



Chapter 4 — The Processor — 20

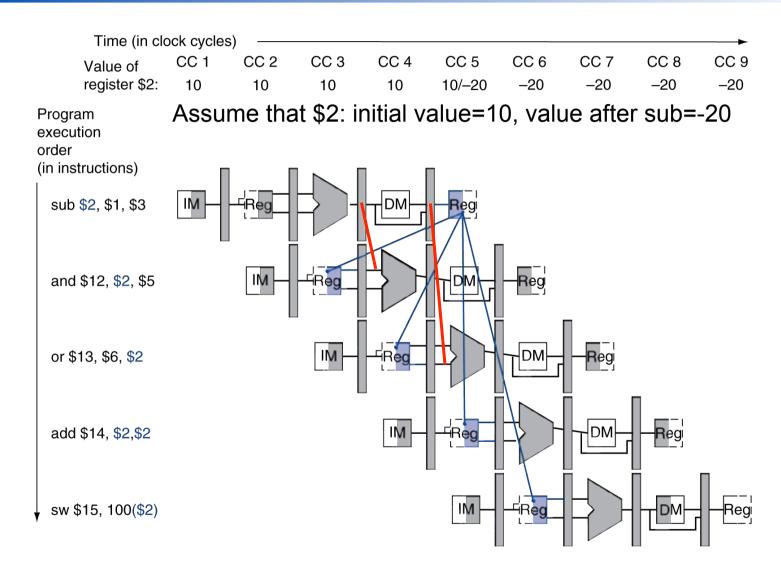
Data Hazards in ALU Instructions

Consider this sequence:

```
sub $2, $1,$3
and $12,$2,$5
or $13,$6,$2
add $14,$2,$2
sw $15,100($2)
```

- We can resolve hazards with forwarding
 - How do we detect when to forward?

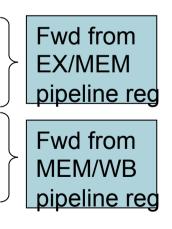
Dependencies & Forwarding



Chapter 4 — The Processor — 22

Detecting the Need to Forward

- Pass register numbers along pipeline
 - e.g., ID/EX.RegisterRs = register number for Rs sitting in ID/EX pipeline register
- ALU operand register numbers in EX stage are given by
 - ID/EX.RegisterRs, ID/EX.RegisterRt
- Data hazards when
 - 1a. EX/MEM.RegisterRd = ID/EX.RegisterRs
 - 1b. EX/MEM.RegisterRd = ID/EX.RegisterRt
 - 2a. MEM/WB.RegisterRd = ID/EX.RegisterRs
 - 2b. MEM/WB.RegisterRd = ID/EX.RegisterRt

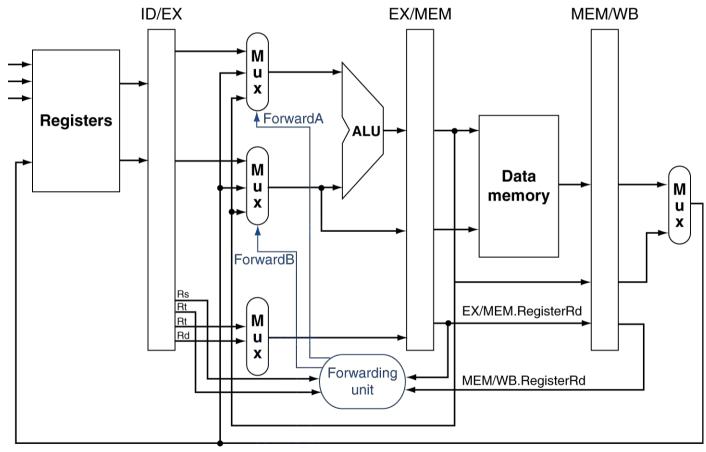


^{*}Recall for R-type: add rd, rs, rt, i.e. ALU uses values of rs and rt registers for calculation. Chapter 4 — The Processor — 23

Detecting the Need to Forward

- But only if forwarding instruction will write to a register!
 - EX/MEM.RegWrite, MEM/WB.RegWrite
- And only if Rd for that instruction is not \$zero
 - EX/MEM.RegisterRd ≠ 0,
 MEM/WB.RegisterRd ≠ 0

Forwarding Paths



b. With forwarding

Forwarding Conditions

EX hazard

if (EX/MEM.RegWrite and (EX/MEM.RegisterRd ≠ 0) and (EX/MEM.RegisterRd = ID/EX.RegisterRs)) ForwardA = 10

if (EX/MEM.RegWrite and (EX/MEM.RegisterRd ≠ 0) and (EX/MEM.RegisterRd = ID/EX.RegisterRt)) ForwardB = 10

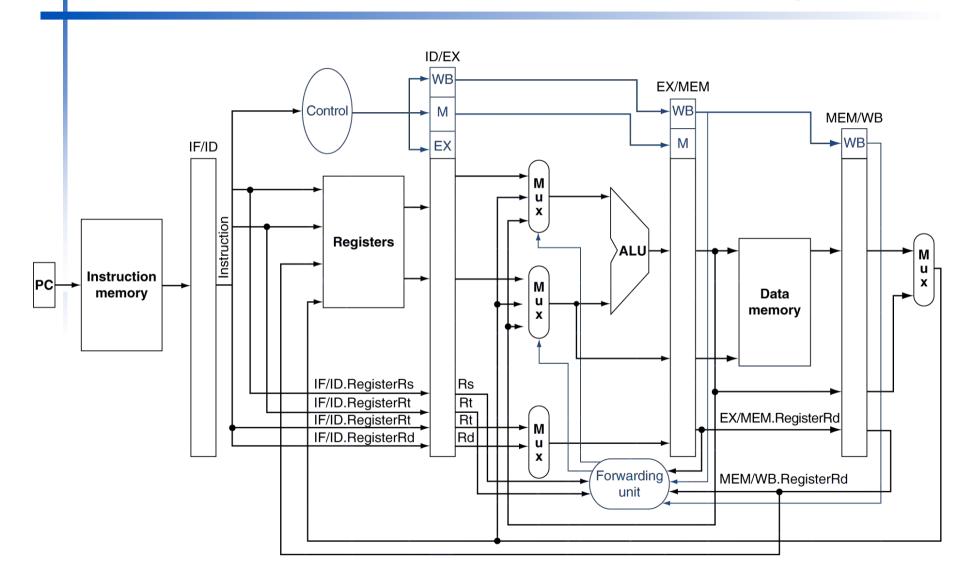
MEM hazard

• if (MEM/WB.RegWrite and (MEM/WB.RegisterRd ≠ 0) and (MEM/WB.RegisterRd = ID/EX.RegisterRs)) ForwardA = 01

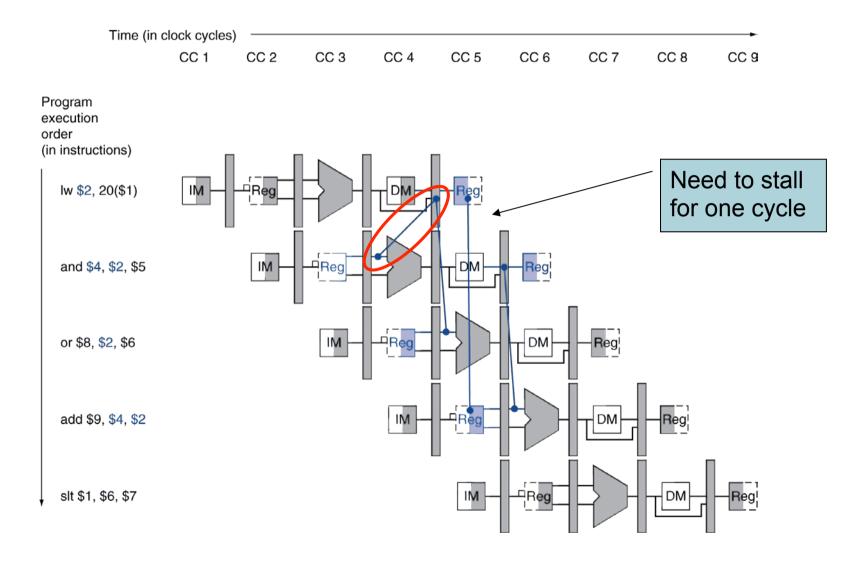
F (NATNAMP PogNA/rite and (NATNA/)

if (MEM/WB.RegWrite and (MEM/WB.RegisterRd ≠ 0) and (MEM/WB.RegisterRd = ID/EX.RegisterRt)) ForwardB = 01

Datapath with Forwarding



Load-Use Data Hazard



Chapter 4 — The Processor — 28

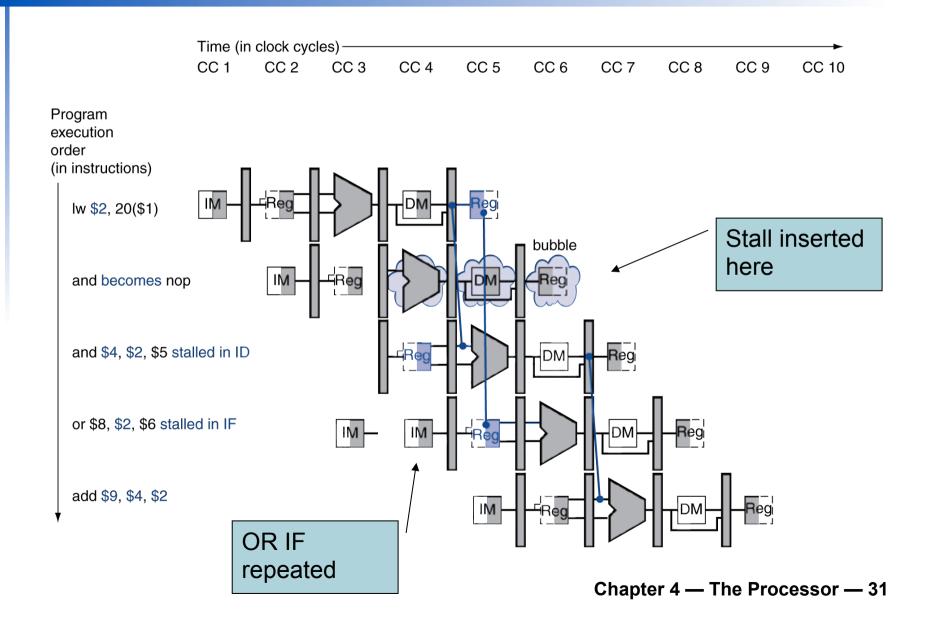
Load-Use Hazard Detection

- Check when using instruction is decoded in ID stage
- ALU operand register numbers in ID stage are given by
 - IF/ID.RegisterRs, IF/ID.RegisterRt
- Load-use hazard when
 - ID/EX.MemRead and ((ID/EX.RegisterRt = IF/ID.RegisterRs) or (ID/EX.RegisterRt = IF/ID.RegisterRt))
- If detected, stall and insert bubble

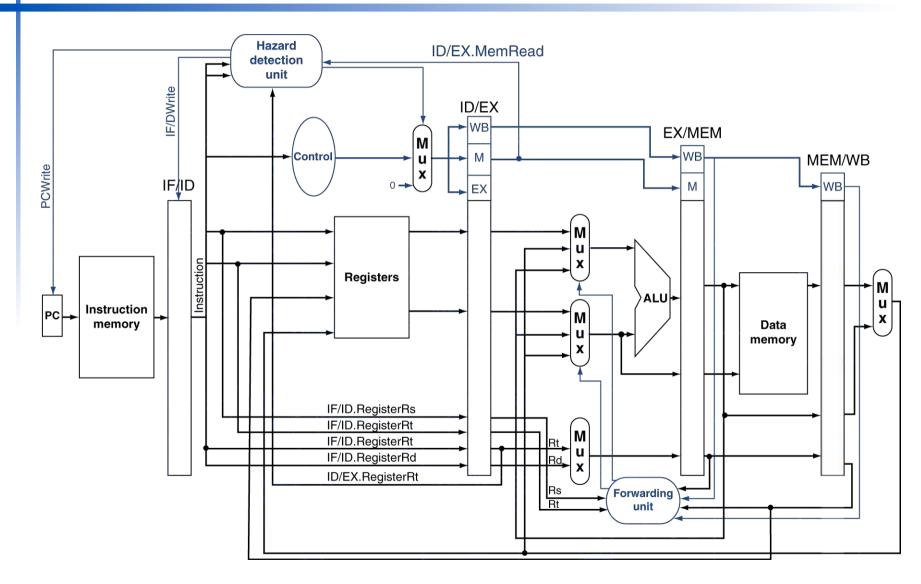
How to Stall the Pipeline

- Force control values in ID/EX register to 0
 - EX, MEM and WB do nop (no-operation)
- Prevent update of PC and IF/ID register
 - Using instruction is decoded again
 - Following instruction is fetched again
 - 1-cycle stall allows MEM to read data for \(\)\rm \
 - Can subsequently forward to EX stage

Stall/Bubble in the Pipeline



Datapath with Hazard Detection

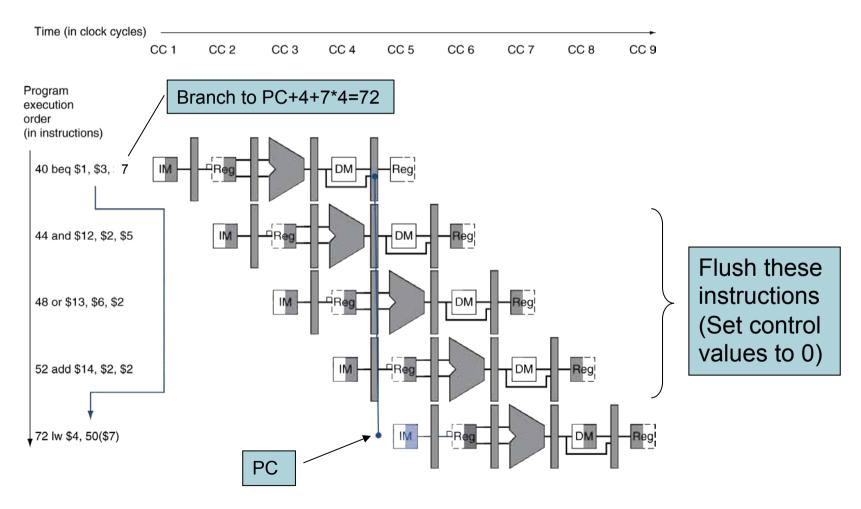


Stalls and Performance

- Stalls reduce performance
 - But are required to get correct results
- Compiler can arrange code to avoid hazards and stalls
 - Requires knowledge of the pipeline structure

Branch Hazards

If branch outcome determined in MEM



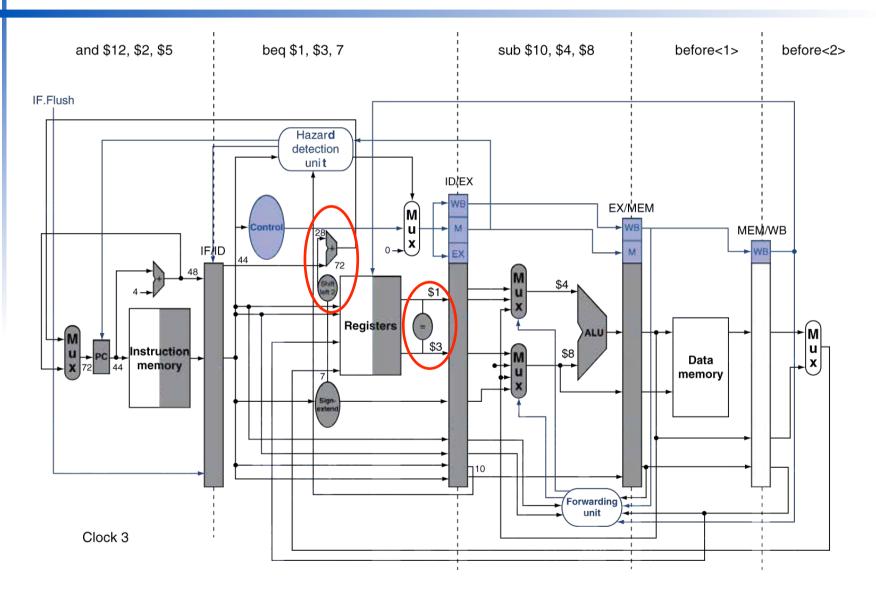
Solution to Control Hazard

Example: branch taken

```
36: sub $10, $4, $8
40: beq $1, $3, 7
44: and $12, $2, $5
48: or $13, $2, $6
52: add $14, $4, $2
56: slt $15, $6, $7
...
72: lw $4, 50($7)
```

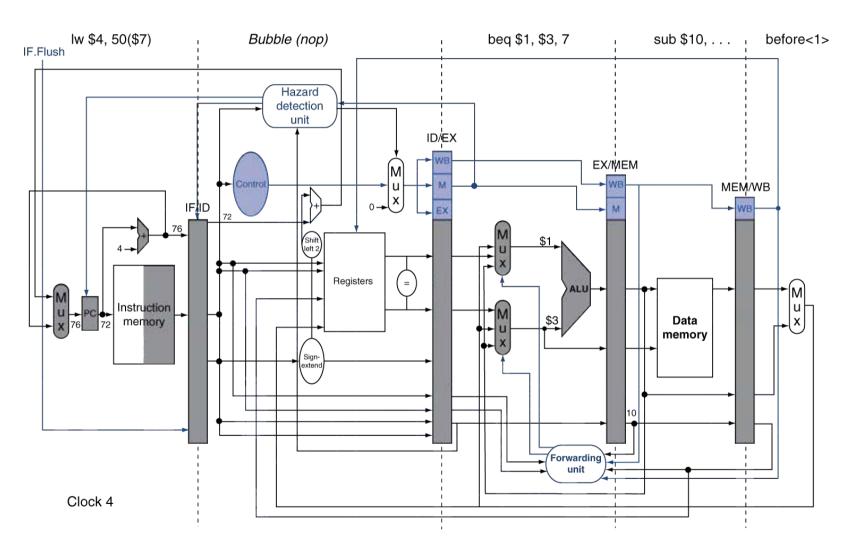
- Assume additional hardware to determine outcome of branch in ID stage
 - Target address adder: PC+4+4*7=72
 - Register comparator: e.g. if \$1=\$3

Example: Branch Taken



Chapter 4 — The Processor — 36

Example: Branch Taken



Chapter 4 — The Processor — 37