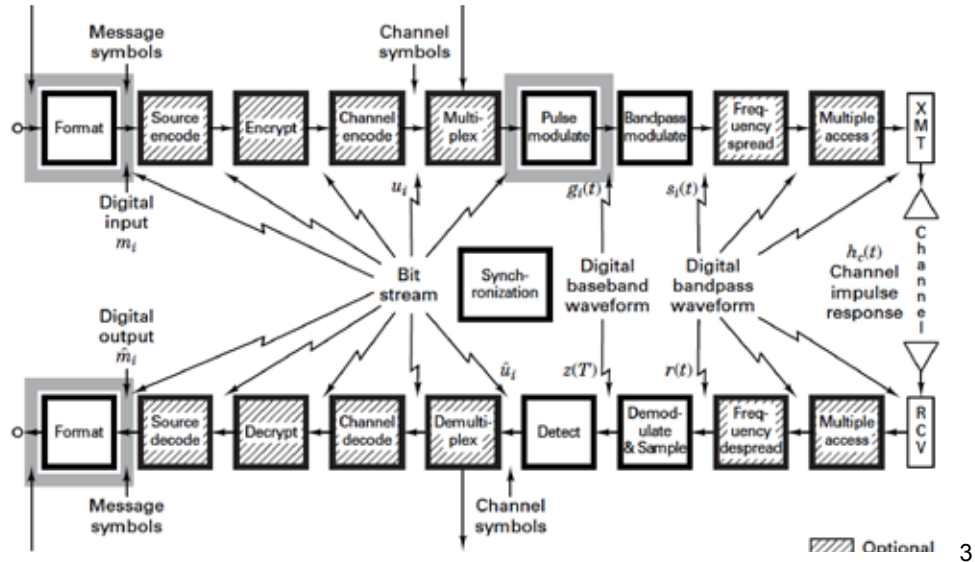


Chapter 2

Formatting and Baseband Modulation

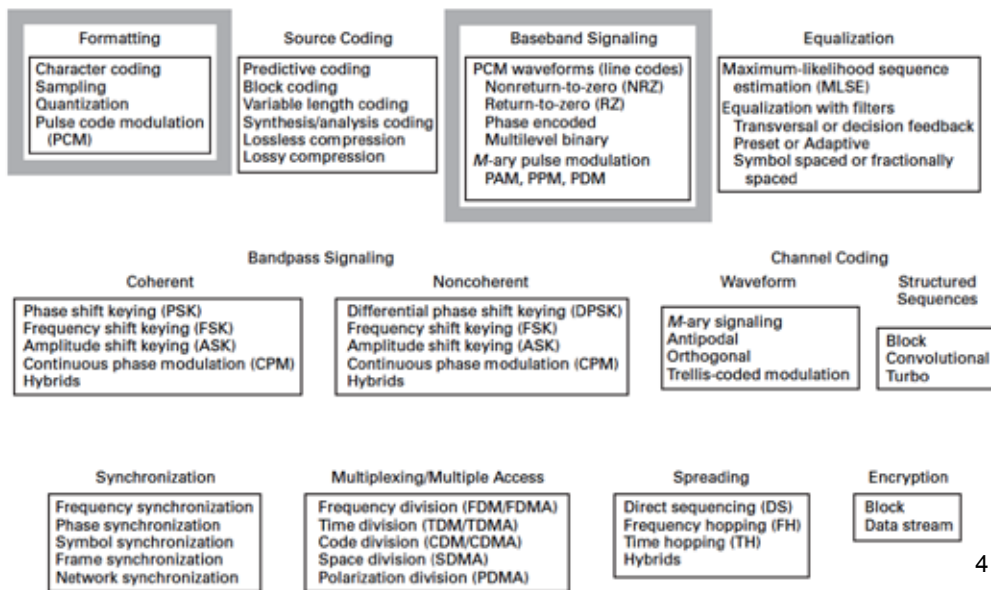
Formatting

Formatting & Baseband



3

Formatting and Baseband



4

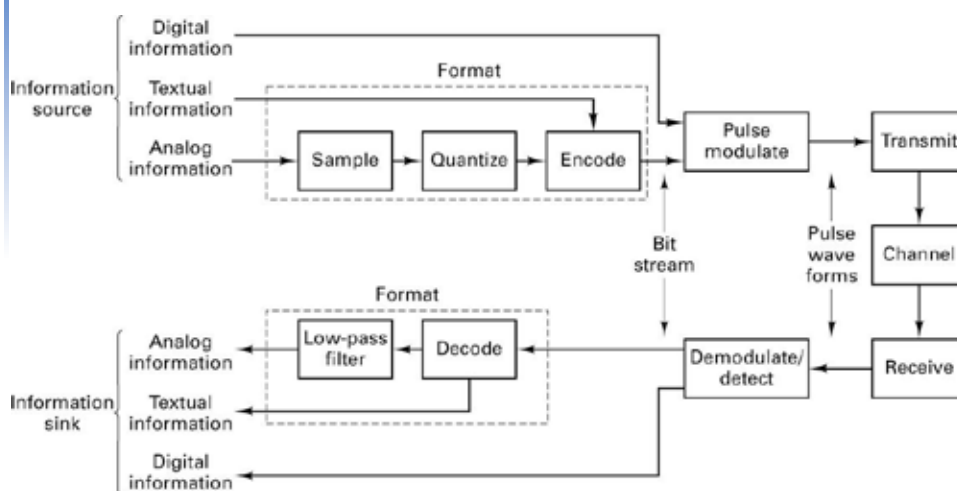
What is Formatting?

- Information can take either of the three forms:
 - Textual information
 - Analog signals
 - Digital data
- Before the signals are transmitted over a digital communication channel, an information bearing signal must be converted to digital symbols (**Formatting**).
- The resulting digital symbols are then represented by baseband waveforms (**Pulse Modulation or Line Coding**).

5

Block Diagram

Block diagram representing formatting and transmission of baseband signals.



6

Textual Data (1)

American Standard Code for Information Interchange (ASCII) for encoding alphanumerics

Bits	5	0	1	0	1	0	1	0	1			
	6	0	0	1	1	0	0	1	1			
1	2	3	4	7	0	0	0	0	1	1	1	1
0 0 0 0	NUL	DLE	SP	0	@	P	'	p	NUL	Null, or all zeros	DC1	Device control 1
1 0 0 0	SOH	DC1	!	1	A	Q	a	q	SOH	Start of heading	DC2	Device control 2
0 1 0 0	STX	DC2	*	2	B	R	b	r	STX	Start of text	DC3	Device control 3
1 1 0 0	ETX	DC3	#	3	C	S	c	s	ETX	End of text	DC4	Device control 4
0 0 1 0	EOT	DC4	\$	4	D	T	d	t	EOT	End of transmission	NAK	Negative acknowledge
1 0 1 0	ENQ	NAK	%	5	E	U	e	u	ENQ	Enquiry	SYN	Synchronous idle
0 1 1 0	ACK	SYN	&	6	F	V	f	v	ACK	Acknowledge	ETB	End of transmission
1 1 1 0	BEL	ETB	'	7	G	W	g	w	BEL	Bell, or alarm	CAN	Cancel
0 0 0 1	BS	CAN	(8	H	X	h	x	BS	Backspace	EM	End of medium
1 0 0 1	HT	EM)	9	I	Y	i	y	HT	Horizontal tabulation	SUB	Substitute
0 1 0 1	LF	SUB	*	:	J	Z	j	z	LF	Line feed	ESC	Escape
1 1 0 1	VT	ESC	+	;	K	[k	{	VT	Vertical tabulation	FS	File separator
0 0 1 1	FF	FS	,	<	L	\	l		FF	Form feed	GS	Group separator
1 0 1 1	CR	GS	-	=	M]	m	}	CR	Carriage return	RS	Record separator
0 1 1 1	SO	RS	.	>	N	^	n	~	SO	Shift out	US	Unit separator
1 1 1 1	SI	US	/	?	O	_	o	DEL	SI	Shift in	SP	Space
									DLE	Data link escape	DEL	Delete

7

Textual Data (2)

Extended Binary Coded Decimal Interchange Information (EBCDIC) for encoding alphanumerics

Bits	5	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1
	6	0	0	0	0	1	1	1	1	0	0	0	0	1	1	1
1	2	3	4	7	0	0	1	1	0	0	1	1	0	0	1	1
8	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1
0 0 0 0	NUL	SOH	STX	ETX	PF	HT	LC	DEL		SMM	VT	FF	CR	SO	SI	
0 0 0 1	DLE	DC1	DC2	DC3	RES	NL	BS	IL	CAN	EM	CC		IFS	IGS	IRS	IUS
0 0 1 0	DS	SOS	FS		BYP	LF	EOB	PRE			SM		ENQ	ACK	BEL	
0 0 1 1			SYN		PN	RS	US	EOT					DC4	NAK	SUB	
0 1 0 0	SP										€		<	(+	!
0 1 0 1	&										!	\$	*)	:	~
0 1 1 0	-	/										,	%	_	>	?
0 1 1 1											:	#	@	'	=	*
1 0 0 0		a	b	c	d	e	f	g	h	i						
1 0 0 1		j	k	l	m	n	o	p	q	r						
1 0 1 0			s	t	u	v	w	x	y	z						
1 0 1 1																
1 1 0 0		A	B	C	D	E	F	G	H	I						
1 1 0 1		J	K	L	M	N	O	P	Q	R						
1 1 1 0			S	T	U	V	W	X	Y	Z						
1 1 1 1	0	1	2	3	4	5	6	7	8	9						

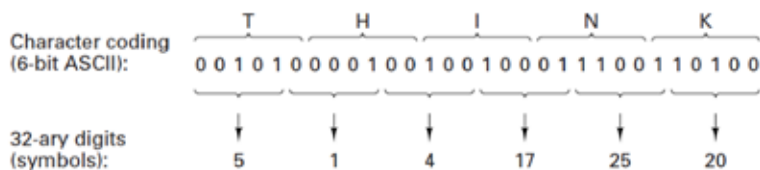
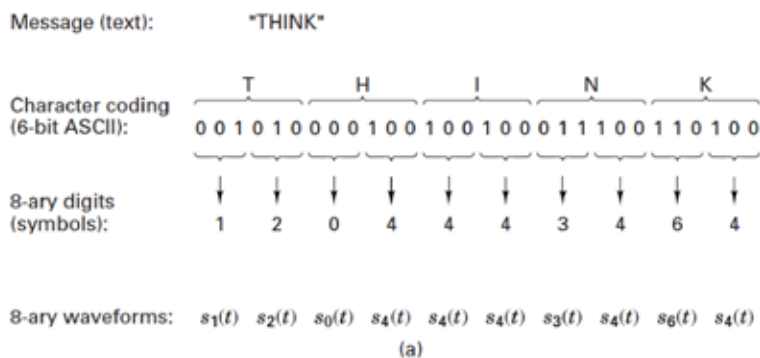
Others Same as ASCII 8

Message and Symbol

- Textual message comprises a sequence of alphanumeric characters.
 - Example: Hello, how are you.
- Textual message is converted into a sequence of bits, i.e. bit stream or baseband signal.
- Symbols are formed by a group of k bits from a finite symbol set of $M=2^k$ such symbols.
- A system using a symbol set size of M is referred to as an M -ary system.

9

Message and Symbol: Example

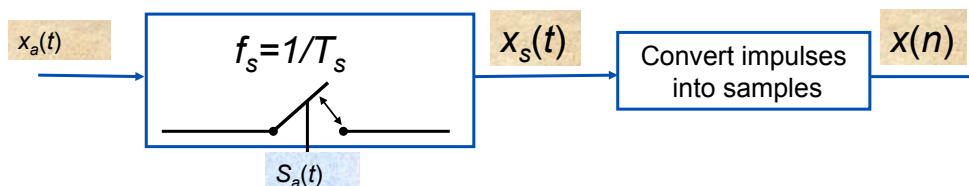


10

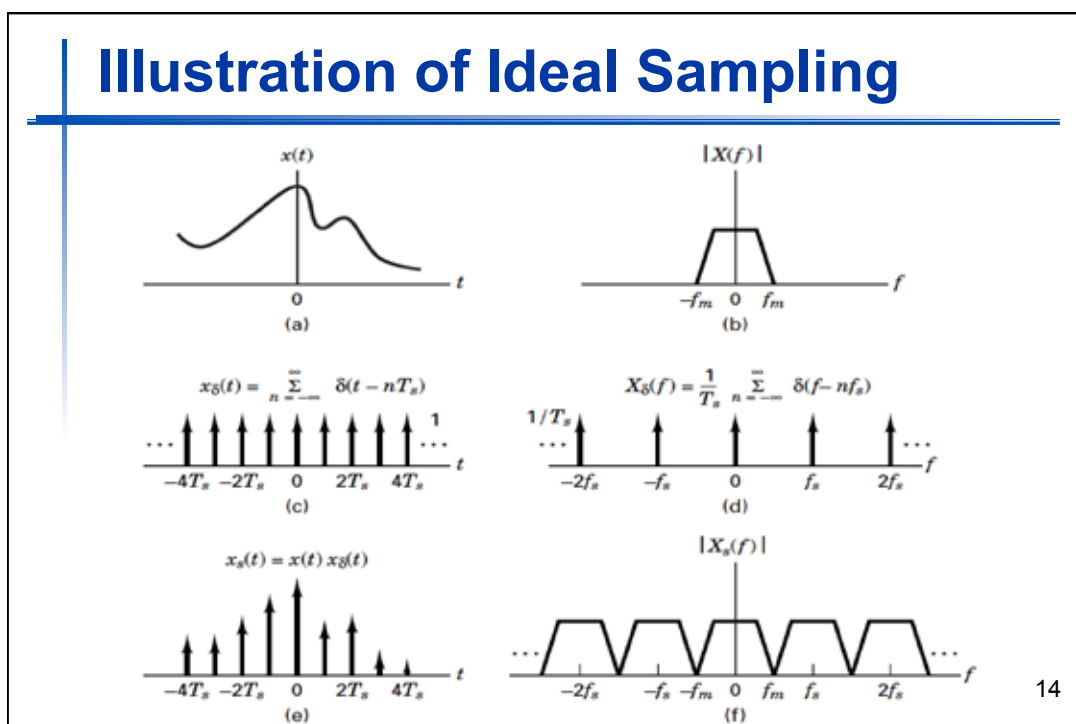
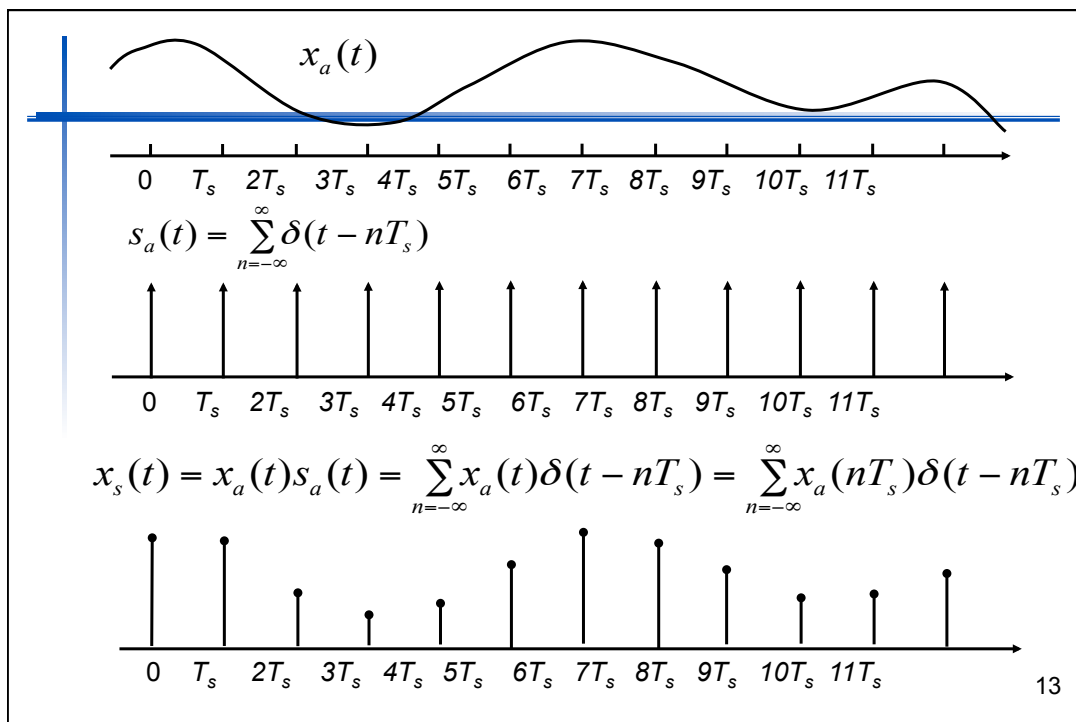
Formatting Analog Information

Periodic Sampling

- Typically, discrete-time signals are formed by periodically sampling a continuous-time signal : $x(n)=x_a(nT_s)$
The sampling interval T_s is the sampling period, and $f_s=1/T_s$ is the sampling frequency in samples per second.
- The sampling process:



12



Fourier Transform of a CT Sampled Signal

- Fourier transform pair:

$$X(\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{j\omega t} d\omega$$

- Fourier transform of sampled signal :

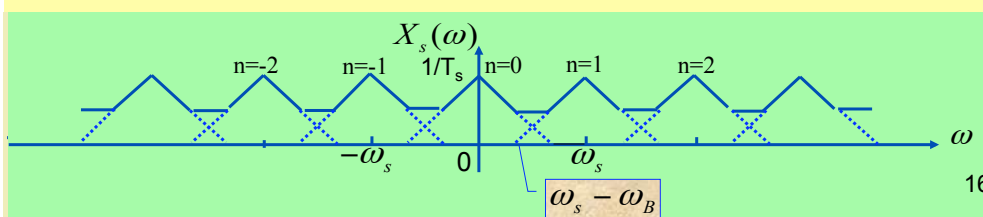
$$X_s(\omega) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} X_a(\omega - n\omega_s), \quad \omega_s = \frac{2\pi}{T_s}$$

15

$$X_s(\omega) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} X_a(\omega - n\omega_s), \quad \omega_s = \frac{2\pi}{T_s}$$

- The Fourier transform of the continuous-time sampled signal $X_s(\omega)$ is a periodic function of ω consisting of a superposition of shifted replicas of $X_a(\omega)$, scaled by $1/T_s$.

The overlap of the Fourier transform of each of the terms of the sampled signal is called aliasing



Sampling Theorem :

- A bandlimited continuous-time signal, with highest frequency (bandwidth) B Hz, can be uniquely recovered from its samples provided that the sampling rate $F_s \geq 2B$ samples per second.
- The frequency $F_s = 2B$ is called the *Nyquist sampling frequency*.
- If the signal is sampled at less than the Nyquist rate, then the *aliasing* occurs.

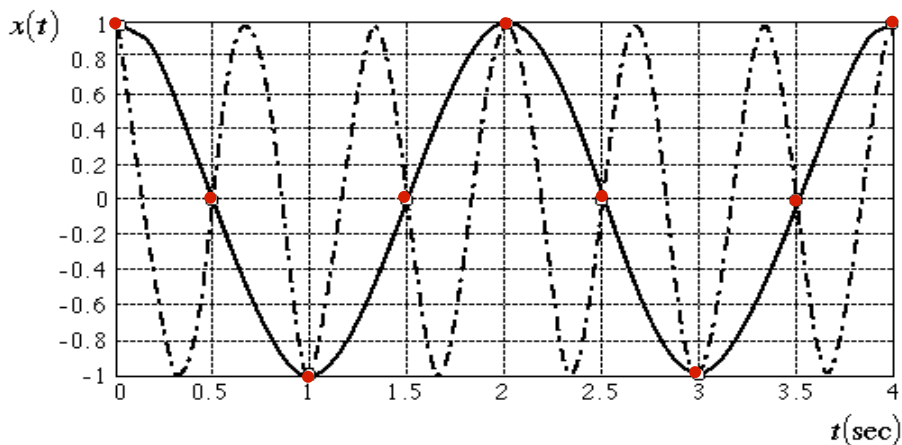
17

Example

——— $x_1(t) = \cos 2\pi F_1 t, \quad F_1 = 0.5 \text{ Hz}$

- - - - $x_2(t) = \cos 2\pi F_2 t, \quad F_2 = 1.5 \text{ Hz}$

$F_s = 2 \text{ samples/sec} \Rightarrow x_1(nT_s) = x_2(nT_s)$



18

Natural Sampling

- Replace impulse train in ideal sampling with a pulse train $p(t)$ (also known as the gating waveform).

- The pulse train

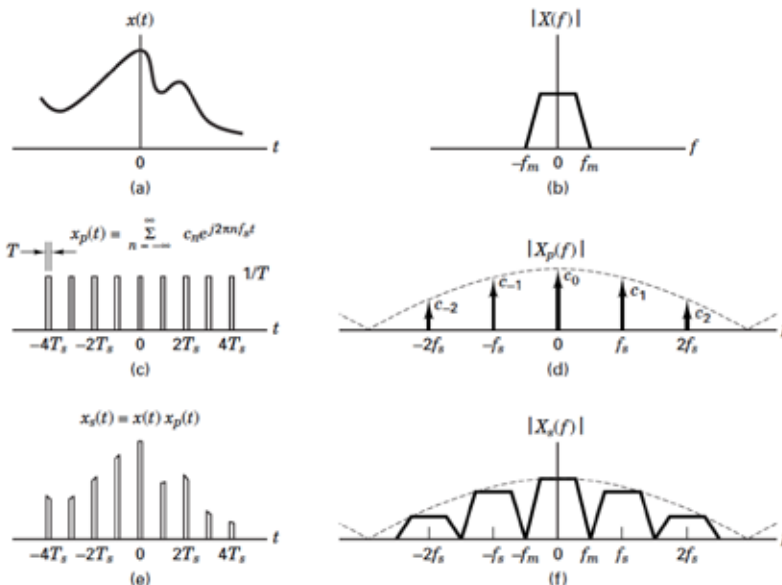
$$p(t) = \sum_{n=-\infty}^{\infty} h(t - nT_s)$$

where $h(t) = 1$ for $0 \leq t \leq \tau$ and $h(t) = 0$ otherwise

- The pulse train can be implemented by an on/off switch.

19

Illustration of Natural Sampling



20

Analog-to-Digital Conversion

- Components : anti-aliasing filter, sample and hold, analog-to-digital converter (quantization).



Block Diagram of an ADC

21

Anti-aliasing Filter

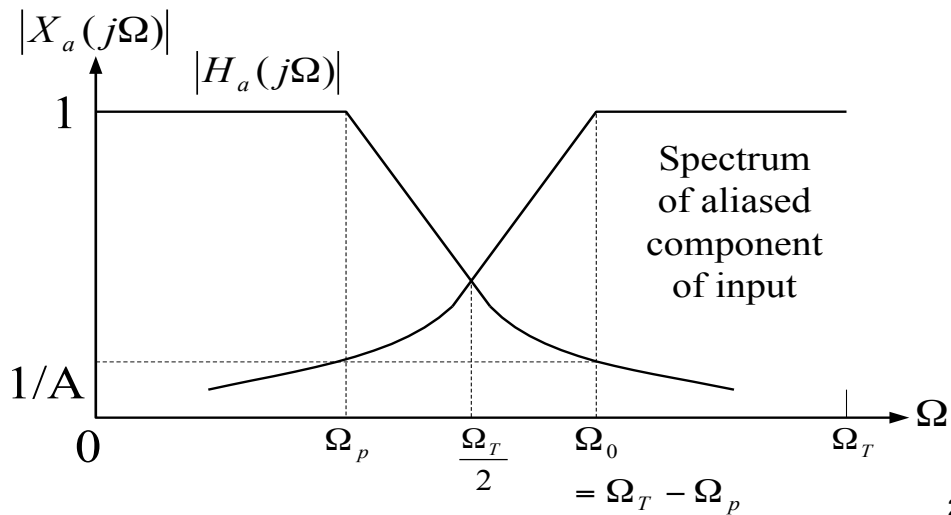
- The role of anti-aliasing filter is to cut off the frequency components that is higher than the half of sampling frequency.
- Ideally, the anti-aliasing filter should have a lowpass frequency response,

$$H_a(j\Omega) = \begin{cases} 1, & |\Omega| < \Omega_T/2 \\ 0, & |\Omega| \geq \Omega_T/2 \end{cases}$$

Such a “brickwall” filter can't be realized using practical analog circuit, hence, must be approximated.

22

Anti-aliasing Filter's Effect on Signal Band



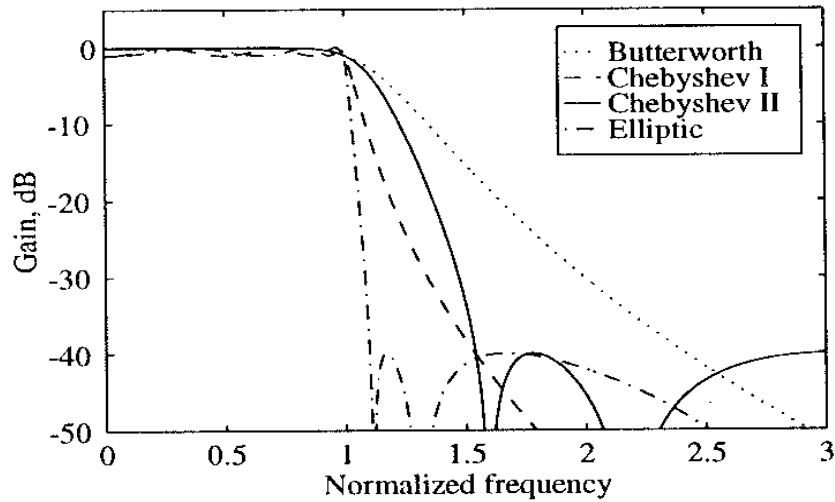
23

Anti-Aliasing Filter Design

- Requirement :
 1. Approximate linear phase in passband
 2. Passband edge $>$ highest frequency in signal
 3. Stopband edge $<$ half of sampling frequency
- Four types of analog filter
 1. Butterworth filter : good passband, slow roll-off
 2. Chebyshev filter : good roll-off and linear phase
 3. Elliptic filter : fast roll-off, non-linear phase
 4. Bessel filter : close to linear phase, wide transitionband
- Design can be done in Matlab

24

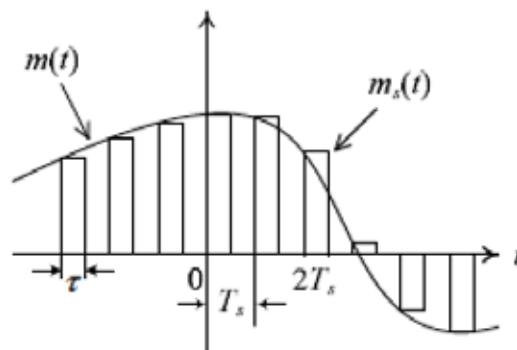
Frequency Response of 4 Types of Filter



25

Sample and Hold

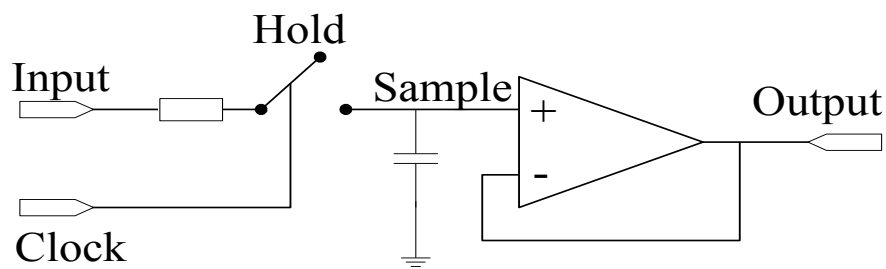
- Sample and hold is the most popular sampling method.
- Involves two operations:
 - Sample and hold



26

Sample and Hold Circuit

- Samples the analog signal at uniform intervals and holds the sampled value after each sampling operation for sufficient time for accurate conversion by the A/D converter.



27

Analog-to-Digital Converter

- Converts an analog signal into a binary coded digital signal.
- Types of A/D converter
 1. Integrating converter
 2. Successive approximation converter
 3. Flash converter
 4. Folding A/D converter
 5. Pipelined A/D converter

28

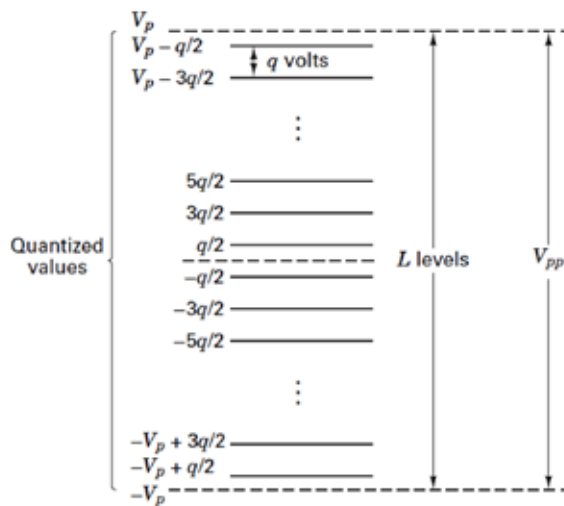
Quantization

A/D Conversion

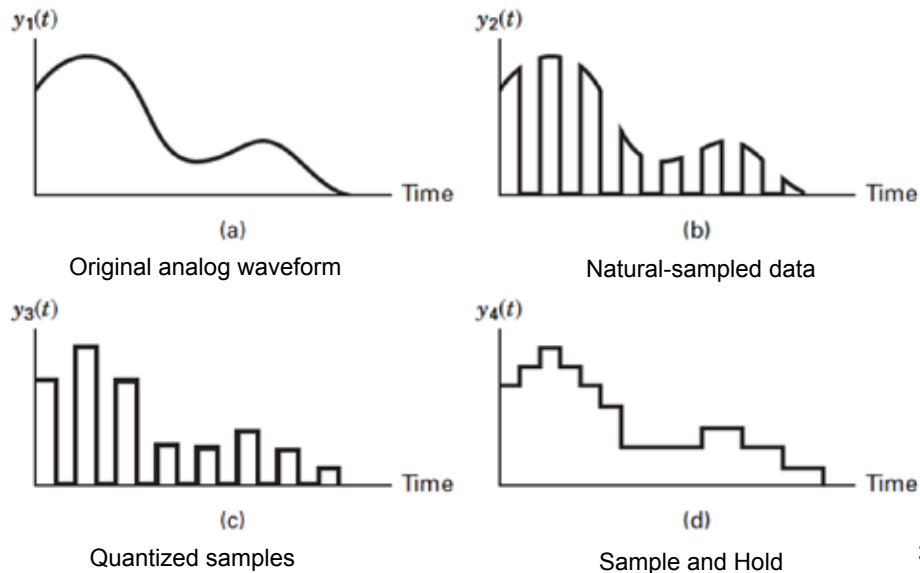
- Uniform quantizer
 - Peak signal power to average quantization noise power is:

$$\left(\frac{S}{N}\right)_q \leq 3L^2$$

- SNR increases as a function of the number of quantization level squared.



Examples of Sampling



31

Pulse Code Modulation (PCM)

- In pulse modulation, some parameter of a pulse train is varied in accordance with the sample values of a message signal.
- Pulse-amplitude modulation (PAM)
 - Amplitudes of regularly spaced pulses are varied.
- Pulse-width modulation (PWM)
 - Widths of the individual pulses are varied.
- Pulse-position modulation (PPM)
 - Position of a pulse relative to its original of occurrence is varied.
- Pulse modulation techniques are still analog modulation. For digital communications of an analog source, quantization of sampled values is needed.

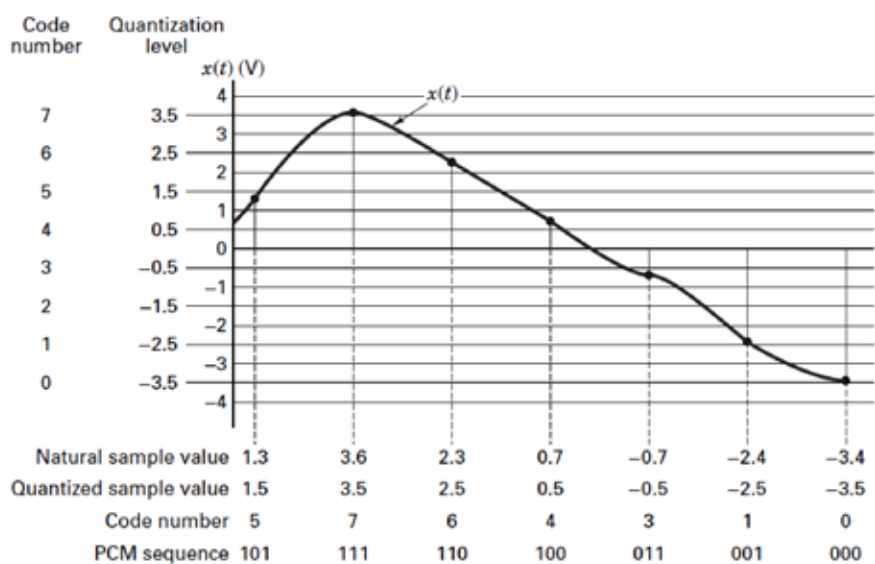
32

PCM

- A PCM signal is obtained from the quantized PAM signal by encoding each quantized sample to a digital codeword
- In binary PCM each quantized sample is digitally encoded into an R -bit binary codeword.
- Binary digits of a PCM signal can be transmitted using many efficient modulation schemes.

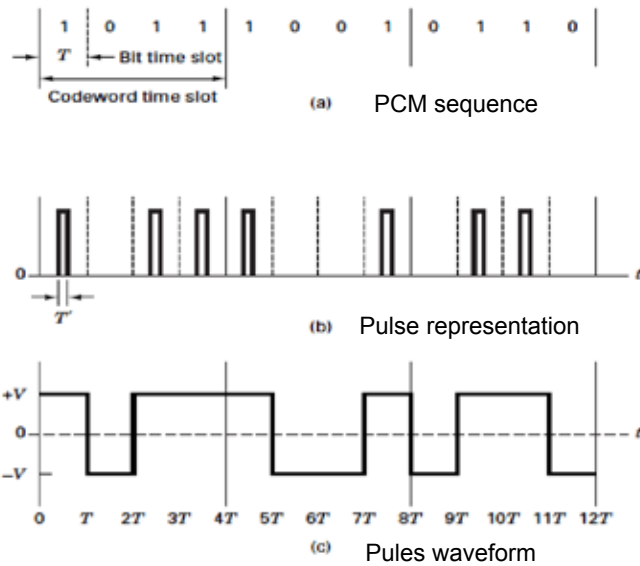
33

PCM - Example



34

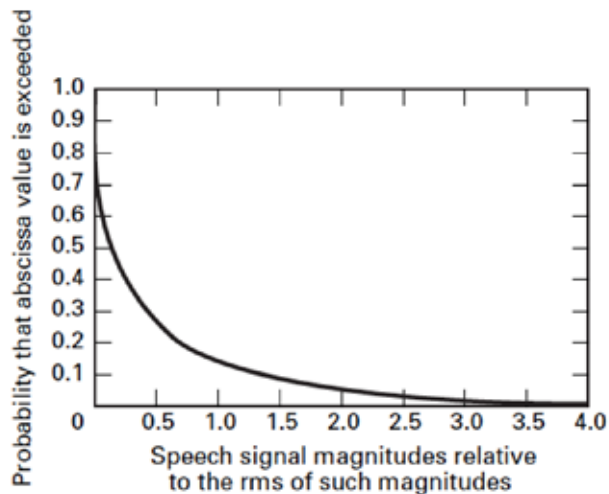
PCM Waveform Example



35

Uniform Quantization (1)

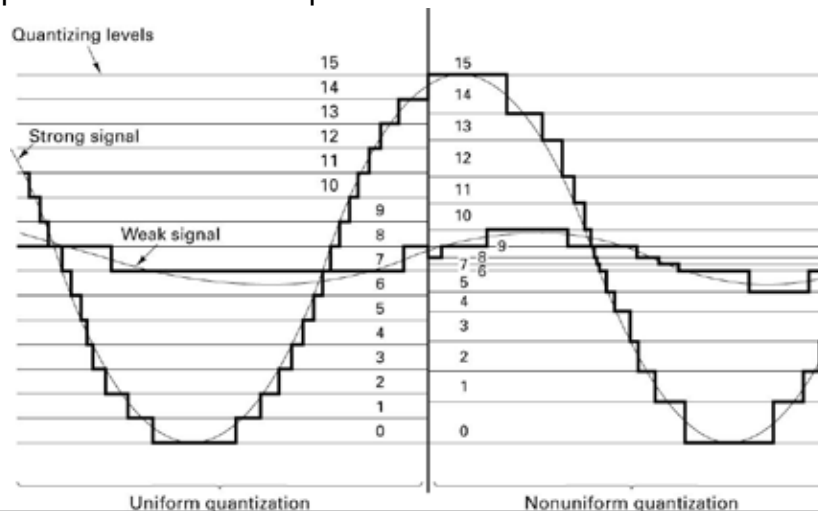
- For most voice communications, very low speech volumes predominate.
- Large amplitudes are very rare while low amplitudes are more often



36

Uniform Quantization (2)

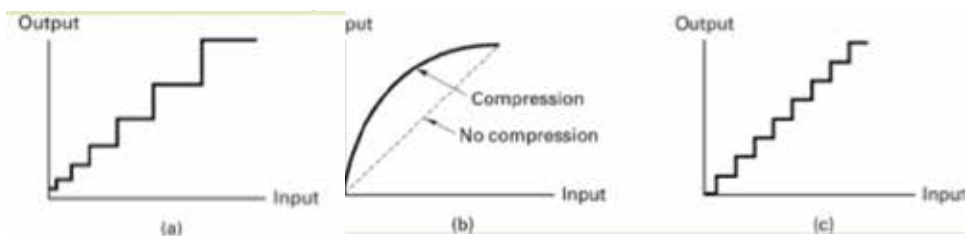
- Using a uniform quantizer for speech signals provides coarse quantization at low amplitudes



37

Nonuniform Quantization (1)

- Nonuniform quantizers are used for speech signals, which provide coarse quantization at high amplitudes and fine quantization at low amplitudes.
- Nonuniform quantization is achieved by the process of companding followed by uniform quantization.

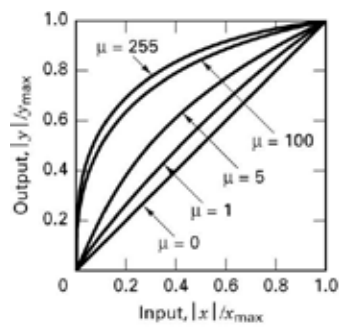


38

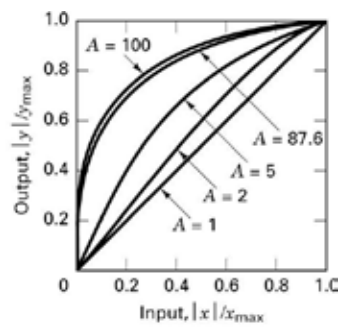
Nonuniform Quantization (2)

- Two commonly used companders are:

μ - law compander	A - law compander
$y = y_{\max} \frac{\log_e [1 + \mu(x /x_{\max})]}{\log_e [1 + \mu]} \operatorname{sgn}(x)$	$y = \begin{cases} y_{\max} \frac{A(x /x_{\max})}{1 + \log_e A} \operatorname{sgn}(x) & 0 < \frac{ x }{x_{\max}} \leq \frac{1}{A} \\ y_{\max} \frac{1 + \log_e [A(x /x_{\max})]}{1 + \log_e A} \operatorname{sgn}(x) & \frac{1}{A} < \frac{ x }{x_{\max}} \leq 1 \end{cases}$



(a)



(b)

39

CSE4214 Digital Communications

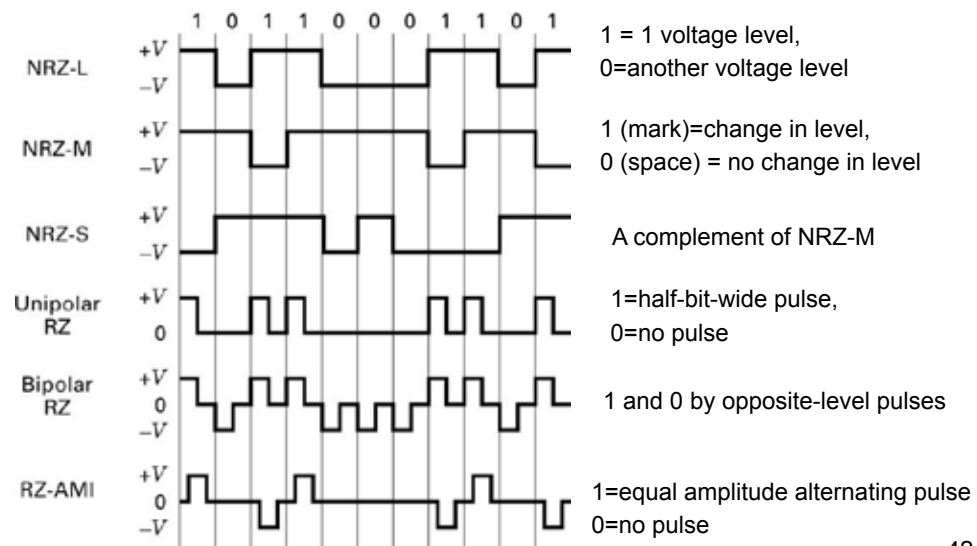
Baseband Transmission

PCM Waveform Types

- Nonreturn-to-zero (NRZ)
 - NRZ is most commonly used PCM waveform
 - NRZ-L (L for level)
 - NRZ-M (M for mark)
 - NRZ-S (S for space)
- Return-to-zero (RZ)
 - Unipolar-RZ, bipolar-RZ, RZ-AMI(alternate mark inversion)
- Phase encoded
- Multilevel binary

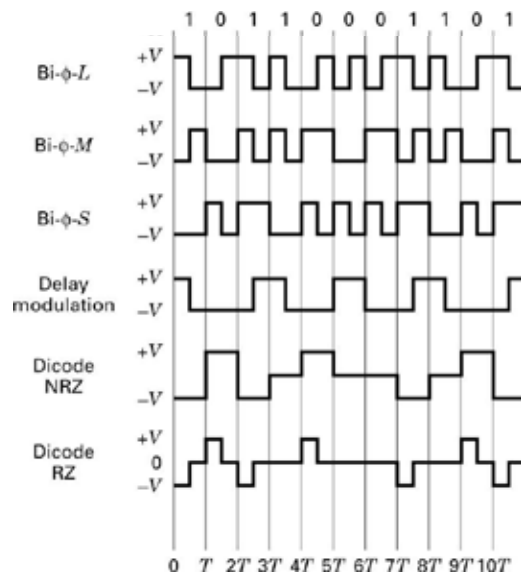
41

PCM Coding (1)



42

PCM Coding (2)



43

Bits per PCM Word and Bits per Symbol

■ PCM word size

- How many bits shall we assign to each analog sample?

$$|e| \leq pV_{pp}$$

$$|e_{\max}| = \frac{q}{2} = \frac{V_{pp}}{2L}$$

$$\frac{V_{pp}}{2L} \leq pV_{pp} \rightarrow 2^l = L \leq \frac{1}{2p}$$

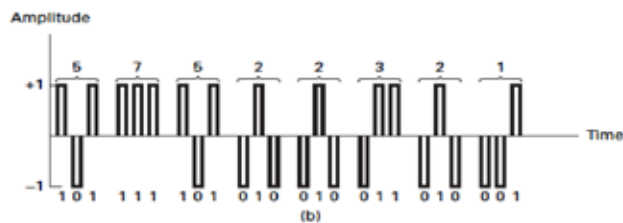
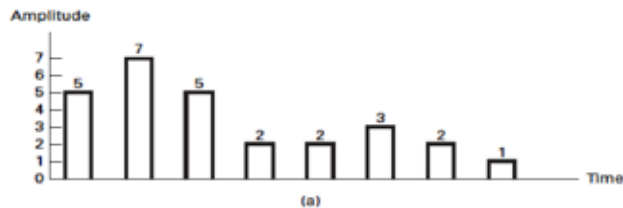
$$l \geq \log_2 \left(\frac{1}{2p} \right)$$

e : quantization error,
 V_{pp} : peak-to-peak voltage
 q : quantization level

44

M-ary Pulse-Modulation

- Multilevel signaling - a group of k -bit is transmitted by $M=2^k$ level pulse.



45

Activity 1

The information in an analog waveform, with maximum frequency $f_m=3\text{kHz}$, is to be transmitted over an M-ary PAM system, where the number of pulse levels is $M=16$. The quantization error is specified not to exceed $(\pm)1\%$ of the peak-to-peak analog signal.

- What is the minimum number of bits/samples, or PCM word size that should be used in digitizing the analog waveform?
- What is the minimum required sampling rate, and what is the resulting bit transmission rate?
- What is the PAM pulse or symbol transmit rate?
- If the transmission bandwidth equals 12 kHz, determine the bandwidth efficiency for this system.

46