

P 9.1 [a] $\omega = 2\pi f = 800 \text{ rad/s}, \quad f = \frac{\omega}{2\pi} = 127.32 \text{ Hz}$

[b] $T = 1/f = 7.85 \text{ ms}$

[c] $I_m = 125 \text{ mA}$

[d] $i(0) = 125 \cos(36.87^\circ) = 100 \text{ mA}$

[e] $\phi = 36.87^\circ; \quad \phi = \frac{36.87^\circ(2\pi)}{360^\circ} = 0.6435 \text{ rad}$

[f] $i = 0$ when $800t + 36.87^\circ = 90^\circ$. Now resolve the units:

$$(800 \text{ rad/s})t = \frac{53.13^\circ}{57.3^\circ/\text{rad}} = 0.927 \text{ rad}, \quad t = 1.16 \text{ ms}$$

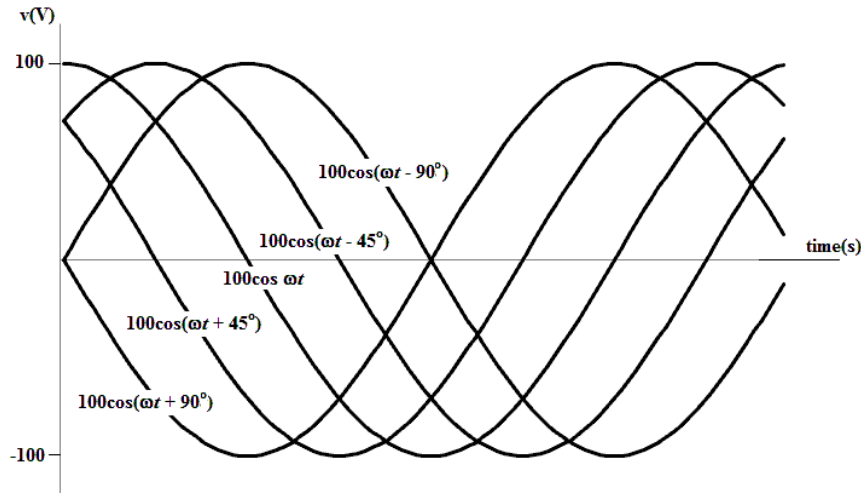
[g] $(di/dt) = (-0.125)800 \sin(800t + 36.87^\circ)$

$$(di/dt) = 0 \quad \text{when} \quad 800t + 36.87^\circ = 180^\circ$$

$$\text{or} \quad 800t = \frac{143.13^\circ}{57.3^\circ/\text{rad}} = 2.498 \text{ rad}$$

$$\text{Therefore} \quad t = 3.12 \text{ ms}$$

P 9.2



[a] Right as ϕ becomes more negative

[b] Left

P 9.5 [a] $\frac{T}{2} = 25 - 5 = 20 \text{ ms}; \quad T = 40 \text{ ms}$

$$f = \frac{1}{T} = \frac{1}{40 \times 10^{-3}} = 25 \text{ Hz}$$

$$[\mathbf{b}] \quad i = I_m \sin(\omega t + \theta)$$

$$\omega = 2\pi f = 50\pi \text{ rad/s}$$

$$50\pi(5 \times 10^{-3}) + \theta = 0; \quad \therefore \quad \theta = \frac{-\pi}{4} \text{ rad} = -45^\circ$$

$$i = I_m \sin[50\pi t - 45^\circ]$$

$$0.5 = I_m \sin -45^\circ; \quad I_m = -70.71 \text{ mA}$$

$$i = -70.71 \sin[50\pi t - 45^\circ] = 70.71 \cos[50\pi t + 45^\circ] \text{ mA}$$

$$\text{P 9.6} \quad V_m = \sqrt{2}V_{\text{rms}} = \sqrt{2}(240) = 339.41 \text{ V}$$

$$\text{P 9.7} \quad V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^{T/2} V_m^2 \sin^2 \frac{2\pi}{T} t \, dt}$$

$$\int_0^{T/2} V_m^2 \sin^2 \left(\frac{2\pi}{T} t \right) dt = \frac{V_m^2}{2} \int_0^{T/2} \left(1 - \cos \frac{4\pi}{T} t \right) dt = \frac{V_m^2 T}{4}$$

$$\text{Therefore} \quad V_{\text{rms}} = \sqrt{\frac{1}{T} \frac{V_m^2 T}{4}} = \frac{V_m}{2}$$

P 9.11 **[a]** $\mathbf{Y} = 30/\underline{-160^\circ} + 15/\underline{70^\circ} = 29.38/\underline{170.56^\circ}$

$$y = 28.38 \cos(200t + 170.56^\circ)$$

[b] $\mathbf{Y} = 90/\underline{-110^\circ} + 60/\underline{-70^\circ} = 141.33/\underline{-94.16^\circ}$

$$y = 141.33 \cos(50t - 94.16^\circ)$$

$$[\text{c}] \quad \mathbf{Y} = 50/\underline{-60^\circ} + 25/\underline{20^\circ} - 75/\underline{-30^\circ} = 16.7/\underline{170.52^\circ}$$

$$y = 16.7 \cos(5000t + 170.52^\circ)$$

$$[\text{d}] \quad \mathbf{Y} = 10/\underline{30^\circ} + 10/\underline{-90^\circ} + 10/\underline{150^\circ} = 0$$

$$y = 0$$

$$\text{P 9.12} \quad [\text{a}] \quad 400 \text{ Hz}$$

$$[\text{b}] \quad \theta_v = 0^\circ$$

$$\mathbf{I} = \frac{100/\underline{0^\circ}}{j\omega L} = \frac{100}{\omega L}/\underline{-90^\circ}; \quad \theta_i = -90^\circ$$

$$[\text{c}] \quad \frac{100}{\omega L} = 20; \quad \omega L = 5 \Omega$$

$$[\text{d}] \quad L = \frac{5}{800\pi} = 1.99 \text{ mH}$$

$$[\text{e}] \quad Z_L = j\omega L = j5 \Omega$$

$$\text{P 9.13} \quad [\text{a}] \quad \omega = 2\pi f = 160\pi \times 10^3 = 502.65 \text{ krad/s} = 502,654.82 \text{ rad/s}$$

$$[\text{b}] \quad \mathbf{I} = \frac{25 \times 10^{-3}/\underline{0^\circ}}{1/j\omega C} = j\omega C(25 \times 10^{-3})/\underline{0^\circ} = 25 \times 10^{-3} \omega C/\underline{90^\circ}$$

$$\therefore \theta_i = 90^\circ$$

$$[\text{c}] \quad 628.32 \times 10^{-6} = 25 \times 10^{-3} \omega C$$

$$\frac{1}{\omega C} = \frac{25 \times 10^{-3}}{628.32 \times 10^{-6}} = 39.79 \Omega, \quad \therefore X_C = -39.79 \Omega$$

$$[\text{d}] \quad C = \frac{1}{39.79(\omega)} = \frac{1}{(39.79)(160\pi \times 10^3)}$$

$$C = 0.05 \times 10^{-6} = 0.05 \mu\text{F}$$

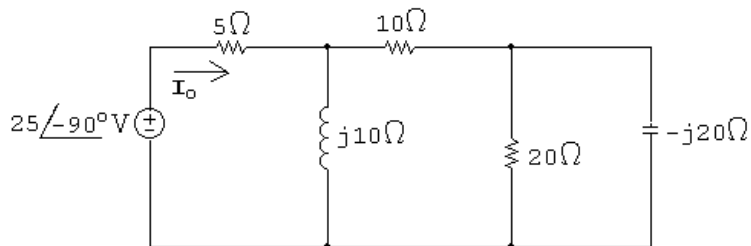
$$[\text{e}] \quad Z_c = j \left(\frac{-1}{\omega C} \right) = -j39.79 \Omega$$

$$\begin{aligned}
 \text{P 9.22} \quad Z_{ab} &= 5 + j8 + 10 \parallel -j20 + (8 + j16) \parallel (40 - j80) \\
 &= 5 + j8 + 8 - j4 + 12 + j16 = 25 + j20 \, \Omega = 32.02 / \underline{38.66^\circ} \, \Omega
 \end{aligned}$$

P 9.30 $\mathbf{V}_s = 25/\underline{-90^\circ} \text{ V}$

$$\frac{1}{j\omega C} = -j20 \Omega$$

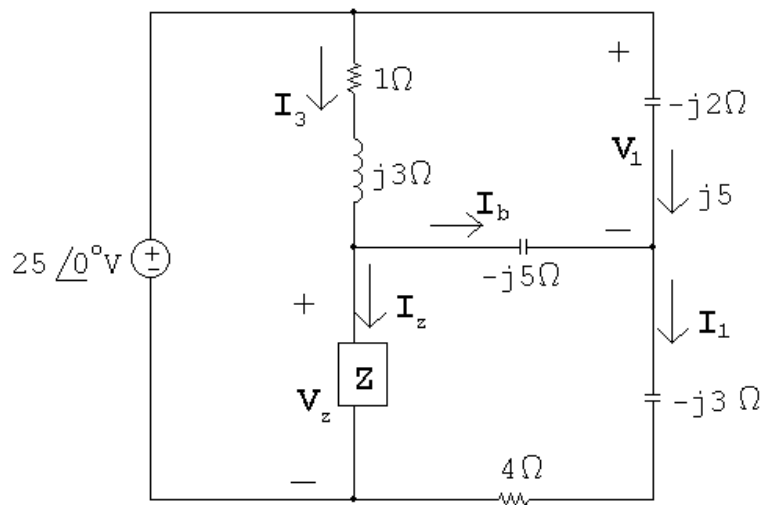
$$j\omega L = j10 \Omega$$



$$Z_{\text{eq}} = 5 + j10 \parallel (10 + 20 \parallel -j20) = 10 + j10 \Omega$$

$$\mathbf{I}_o = \frac{\mathbf{V}_o}{Z_{\text{eq}}} = \frac{25/\underline{-90^\circ}}{10 + j10} = -1.25 - j1.25 = 1.77/\underline{-135^\circ} \text{ A}$$

$$i_o = 1.77 \cos(4000t - 135^\circ) \text{ A}$$



$$\mathbf{V}_1 = j5(-j2) = 10 \text{ V}$$

$$-25 + 10 + (4 - j3)\mathbf{I}_1 = 0 \quad \therefore \quad \mathbf{I}_1 = \frac{15}{4 - j3} = 2.4 + j1.8 \text{ A}$$

$$\mathbf{I}_b = \mathbf{I}_1 - j5 = (2.4 + j1.8) - j5 = 2.4 - j3.2 \text{ A}$$

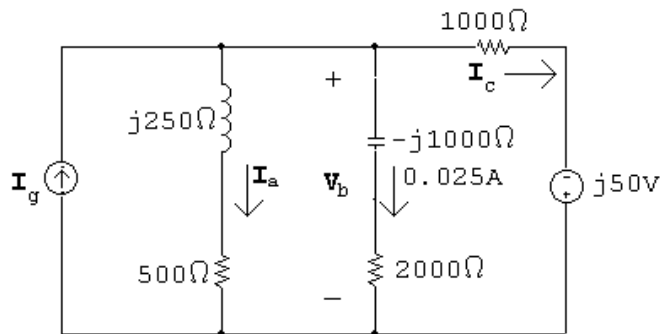
$$\mathbf{V}_Z = -j5\mathbf{I}_2 + (4 - j3)\mathbf{I}_1 = -j5(2.4 - j3.2) + (4 - j3)(2.4 + j1.8) = -1 - j12 \text{ V}$$

$$-25 + (1 + j3)\mathbf{I}_3 + (-1 - j12) = 0 \quad \therefore \quad \mathbf{I}_3 = 6.2 - j6.6 \text{ A}$$

$$\mathbf{I}_Z = \mathbf{I}_3 - \mathbf{I}_2 = (6.2 - j6.6) - (2.4 - j3.2) = 3.8 - j3.4 \text{ A}$$

$$\mathbf{Z} = \frac{\mathbf{V}_Z}{\mathbf{I}_Z} = \frac{-1 - j12}{3.8 - j3.4} = 1.42 - j1.88 \Omega$$

P 9.36 [a]



$$\mathbf{V}_b = (2000 - j1000)(0.025) = 50 - j25 \text{ V}$$

$$\mathbf{I}_a = \frac{50 - j25}{500 + j250} = 60 - j80 \text{ mA} = 100/\underline{-53.13^\circ} \text{ mA}$$

$$\mathbf{I}_c = \frac{50 - j25 + j50}{1000} = 50 + j25 \text{ mA} = 55.9/\underline{26.57^\circ} \text{ mA}$$

$$\mathbf{I}_g = \mathbf{I}_a + \mathbf{I}_b + \mathbf{I}_c = 135 - j55 \text{ mA} = 145.77/\underline{-22.17^\circ} \text{ mA}$$

$$[\mathbf{b}] \quad i_a = 100 \cos(1500t - 53.13^\circ) \text{ mA}$$

$$i_c = 55.9 \cos(1500t + 26.57^\circ) \text{ mA}$$

$$i_g = 145.77 \cos(1500t - 22.17^\circ) \text{ mA}$$

P 9.37 $[\mathbf{a}]$ In order for v_g and i_g to be in phase, the impedance to the right of the 500Ω resistor must be purely real:

$$\begin{aligned} Z_{\text{eq}} &= j\omega L \parallel (R + 1/\omega C) = \frac{j\omega L(R + 1/j\omega C)}{j\omega L + R + 1/j\omega C} \\ &= \frac{j\omega L(j\omega RC + 1)}{j\omega RC - \omega^2 LC + 1} \\ &= \frac{(-\omega^2 RLC + j\omega L)(1 - \omega^2 LC - j\omega RC)}{(1 - \omega^2 LC + j\omega RC)(1 - \omega^2 LC - j\omega RC)} \end{aligned}$$

The denominator of the above expression is purely real. Now set the imaginary part of the numerator in that expression to zero and solve for ω :

$$\omega L(1 - \omega^2 LC) + \omega^3 R^2 l C^2 = 0$$

$$\text{So} \quad \omega^2 = \frac{1}{LC - R^2 C^2} = \frac{1}{(0.2)(10^{-6}) - 200^2(10^{-6})^2} = 6,250,000$$

$$\therefore \quad \omega = 2500 \text{ rad/s} \quad \text{and} \quad f = 397.9 \text{ Hz}$$

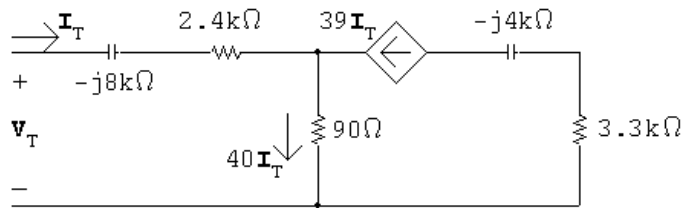
$$[\mathbf{b}] \quad Z_{\text{eq}} = 500 + j500 \parallel (200 - j400) = 1500 \Omega$$

$$\mathbf{I}_g = \frac{90 \angle 0^\circ}{1500} = 60 \angle 0^\circ \text{ mA}$$

$$i_g(t) = 60 \cos 2500t \text{ mA}$$

$$\text{P 9.53} \quad \frac{1}{\omega C_1} = \frac{10^9}{50,000(2.5)} = 8 \text{ k}\Omega$$

$$\frac{1}{\omega C_2} = \frac{10^9}{50,000(5)} = 4 \text{ k}\Omega$$



$$\mathbf{V}_T = (2400 - j8000)\mathbf{I}_T + 40\mathbf{I}_T(90)$$

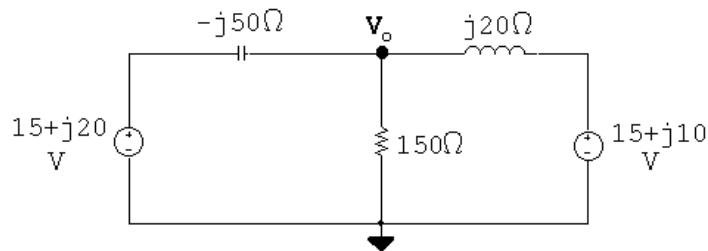
$$Z_{\text{Th}} = \frac{\mathbf{V}_T}{\mathbf{I}_T} = 6000 - j8000 \Omega$$

$$\text{P 9.57} \quad j\omega L = j(400)(50 \times 10^{-3}) = j20 \, \Omega$$

$$\frac{1}{j\omega C} = \frac{-j}{(400)(50 \times 10^{-6})} = -j50 \, \Omega$$

$$\mathbf{V}_{g1} = 25/\underline{53.13^\circ} = 15 + j20 \, \text{V}$$

$$\mathbf{V}_{g2} = 18.03/\underline{33.69^\circ} = 15 + j10 \, \text{V}$$



$$\frac{\mathbf{V}_o - (15 + j20)}{-j50} + \frac{\mathbf{V}_o}{150} + \frac{\mathbf{V}_o - (15 + j10)}{j20} = 0$$

Solving,

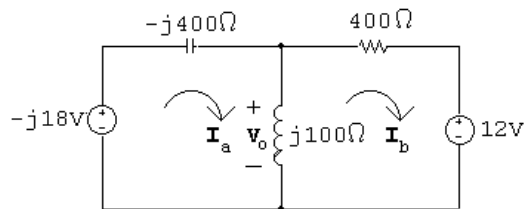
$$\mathbf{V}_o = 15/\underline{0^\circ}$$

$$v_o(t) = 15 \cos 400t \, \text{V}$$

P 9.63 $\mathbf{V}_a = -j18 \text{ V}; \quad \mathbf{V}_b = 12 \text{ V}$

$$j\omega L = j(4000)(25 \times 10^{-3}) = j100\Omega$$

$$\frac{-j}{\omega C} = \frac{-j}{4000(625 \times 10^{-6})} = -j400\Omega$$



$$-j18 = -j300\mathbf{I}_a - j100\mathbf{I}_b$$

$$-12 = -j100\mathbf{I}_a + (400 + j100)\mathbf{I}_b$$

Solving,

$$\mathbf{I}_a = 67.5 - j7.5 \text{ mA}; \quad \mathbf{I}_b = -22.5 + j22.5 \text{ mA}$$

$$\mathbf{V}_o = j100(\mathbf{I}_a - \mathbf{I}_b) = 3 + j9 = 9.49/\underline{71.57^\circ} \text{ A}$$

$$v_o(t) = 9.49 \cos(4000t + 71.57^\circ) \text{ A}$$