# Concurrent Object Oriented Languages 

## Binary Decision Diagrams

https://wiki.cse.yorku.ca/course/6490A

## Model checking

- Explicit: states and transitions are represented explicitly. Drawback: the state space of interesting systems is usually too large to represent explicitly.
- Symbolic: (sets of) states and (sets of) transitions are represented symbolically.

Key idea: exploit the fact that the state space of most systems is not random.
We focus on one symbolic approach:

- BDD based


## Satisfiability

Cook's theorem
Satisfiability checking of Boolean expressions is NP-complete.

## Stephen Cook

- recipient of the ACM Turing award (1982)
- fellow of the Royal Society of London (1998)
- fellow of the Royal Society of Canada (1984)
- member of the National Academy of Sciences (1985)
- member of the American Academy of Arts and Sciences (1986)


Source: Jiri Janicek

## Tautology

## Theorem

Tautology checking of Boolean expressions is co-NP-complete.

## Disjunctive normal form

## Definition

A literal is a variable or its negation.

## Definition

A Boolean expression is in disjunctive normal form (DNF) if it is a disjunction of conjunctions of literals.

## Proposition

Any Boolean expression is equivalent to one in DNF.

## Proposition

Satisfiability checking of Boolean expressions in DNF is in P.

## Proposition

Tautology checking of Boolean expressions in DNF is co-NP-complete.

## Conjunctive normal form

## Definition

A clause is a disjunction of literals.

## Definition

A Boolean expression is in conjunctive normal form (CNF) if it is a conjunction of clauses.

## Proposition

Any Boolean expression is equivalent to one in CNF.

## Proposition

Satisfiability checking of Boolean expressions in CNF is NP-complete.

## Proposition

Tautology checking of Boolean expressions in CNF is in P.

## Notation

$$
\begin{array}{rll}
0 & : & \text { false } \\
1 & : & \text { true } \\
x \rightarrow t_{1}, t_{0} & : & \left(x \wedge t_{1}\right) \vee\left(\neg x \wedge t_{0}\right)
\end{array}
$$

## Definition

The set of Boolean expressions in if-then-else normal form (INF) is defined by

$$
t::=0|1| x \rightarrow t, t
$$

Question
Give a Boolean expression in INF equivalent to $x_{1} \wedge\left(\neg x_{2} \vee x_{3}\right)$.

## Question

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## Answer

$$
\begin{aligned}
t & =x_{1} \rightarrow t_{1}, t_{0} \\
t_{0} & =x_{2} \rightarrow t_{01}, t_{00} \\
t_{1} & =x_{2} \rightarrow t_{11}, t_{10} \\
t_{00} & =x_{3} \rightarrow 0,0 \\
t_{01} & =x_{3} \rightarrow 0,0 \\
t_{10} & =x_{3} \rightarrow 1,1 \\
t_{11} & =x_{3} \rightarrow 1,0
\end{aligned}
$$

## If-then-else normal form

## Shannon's expansion theorem

For every Boolean expression $t$ and variable $x$,

$$
t=x \rightarrow t[1 / x], t[0 / x] .
$$

## Proposition

Any Boolean expression is equivalent to one in INF.

## Decision trees

Boolean expressions in INF can be viewed as binary trees known as decision trees.

Two types of leaves: 0 and 1

$$
\begin{array}{ll}
\hline 0 & 1 \\
\hline
\end{array}
$$

One type of internal nodes: $x \rightarrow t_{1}, t_{0}$


## Decision trees

## Question

Draw the decision tree for the Boolean expression in INF equivalent to $x_{1} \wedge\left(\neg x_{2} \vee x_{3}\right)$.

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\end{aligned}
$$

## Question

Identify all equal subexpressions.

$$
\begin{aligned}
t & =x_{1} \rightarrow t_{1}, t_{0} \\
t_{0} & =x_{2} \rightarrow t_{01}, t_{00} \\
t_{1} & =x_{2} \rightarrow t_{11}, t_{10} \\
t_{00} & =x_{3} \rightarrow 0,0 \\
t_{01} & =x_{3} \rightarrow 0,0 \\
t_{10} & =x_{3} \rightarrow 1,1 \\
t_{11} & =x_{3} \rightarrow 1,0
\end{aligned}
$$

## Question

Identify all equal subexpressions.

## Answer

There are multiple occurrences of 0 and 1 . Furthermore, $t_{00}$ and $t_{01}$ are equal.

## Binary decision diagram

## Question

Identify the equal subtrees in the decision tree for the Boolean expression in INF equivalent to $x_{1} \wedge\left(\neg x_{2} \vee x_{3}\right)$.

## Binary decision diagram

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Identify the equal subtrees in the decision tree for the Boolean expression in INF equivalent to $x_{1} \wedge\left(\neg x_{2} \vee x_{3}\right)$.

## Answer



## Binary decision diagram

## Definition

A binary decision diagram ( $B D D$ ) is a rooted directed acyclic graph where

- two (external) nodes where have out-degree zero and are labelled 0 and 1,
- and all other (internal) nodes have out-degree two, with one outgoing edge called the low edge and the other called the high edge, and are labelled with a variable.


## Binary decision diagram

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- two (external) nodes where have out-degree zero and are labelled 0 and 1,
- and all other (internal) nodes have out-degree two, with one outgoing edge called the low edge and the other called the high edge, and are labelled with a variable.


## Notation

Let $u$ be an internal node.
$\operatorname{var}(u)$ denotes the variable with which node $u$ is labelled.
low ( $u$ ) denotes the successor of node $u$ along its low edge (corresponding to the case that value of $\operatorname{var}(u)$ is low, that is, 0 ). high( $u$ ) denotes the successor of node $u$ along its high edge (corresponding to the case that value of $\operatorname{var}(u)$ is high, that is, 1 ).

## Ordered binary decision diagrams

## Definition

A BDD is ordered if on all paths through the graph the variables respect a given linear order $x_{1}<x_{2}<\cdots<x_{n}$.

## Question

Is the BDD

ordered?

## Reduced ordered binary decision diagrams

## Definition

An ordered BDD is reduced if

- unique: no two distinct internal nodes $u$ and $v$ have the same variable, low- and high-successor, that is,
if $\operatorname{var}(v)=\operatorname{var}(u), \operatorname{low}(v)=\operatorname{low}(u)$, and $\operatorname{high}(v)=\operatorname{high}(u)$ then $u=v$.
- non-redundant: no internal node $u$ has identical low- and high-successor, that is,

$$
\operatorname{low}(u) \neq \operatorname{high}(u) .
$$

## Reduced ordered binary decision diagrams

## Question

Is the ordered BDD

reduced?

## Reduced ordered binary decision diagrams

Question
What is the corresponding reduced ordered BDD?

## Reduced ordered binary decision diagrams

## Question

What is the corresponding reduced ordered BDD?

Answer


## Canonicity lemma

## Lemma

For a Boolean expression $t$ with variables $x_{1}, x_{2}, \ldots, x_{n}$ and a linear order $x_{1}<x_{2}<\cdots<x_{n}$, there exists a unique reduced ordered BDD which is equivalent to $t$.

For the remainder, we restrict our attention to reduced ordered BDDs and simply call them BDDs.

## Randal Bryant

- member of the National Academy of Engineering (2003),
- recipient of the Paris Kanellakis Theory and Practice Award (1997)
- recipient of the IEEE Emanuel R. Piore Award (2007)
- his paper on BDDs is one of the most cited computer science papers (more than 8000 citations)


Source: Randal Bryant

## BDDs

## Proposition <br> Satisfiability checking of BDDs is constant time.

## Proposition

Tautology checking of BDDs is constant time.

The variable order matters

## Question

Draw the BDD corresponding to

$$
\left(x_{1} \wedge x_{2}\right) \vee\left(x_{3} \wedge x_{4}\right) \vee\left(x_{5} \wedge x_{6}\right)
$$

for the variable ordering

$$
x_{1}<x_{2}<x_{3}<x_{4}<x_{5}<x_{6}
$$

The variable order matters

## Question

Draw the BDD corresponding to

$$
\left(x_{1} \wedge x_{2}\right) \vee\left(x_{3} \wedge x_{4}\right) \vee\left(x_{5} \wedge x_{6}\right)
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for the variable ordering

$$
x_{1}<x_{4}<x_{5}<x_{2}<x_{3}<x_{6}
$$

## The variable order matters

## Theorem <br> Deciding whether a given variable order is optimal is NP-hard.

Heuristics are used to find good variable orderings. For more details, see, for example,
I. Wegener. Branching Programs and Binary Decision Diagrams:

Theory and Applications. 2000.

## Data structures for BDDs

The nodes are represented as integers $0,1,2, \ldots$ where 0 and 1 represent the leaves labelled 0 and 1 .

Given a variable ordering $x_{1}<x_{2}<\cdots<x_{n}$, the variables are represented by their indices $0,1, \ldots, n$.

## Node table

The node table can be viewed as a partial function

$$
T: \mathbb{N} \rightarrow\left(\mathbb{N}^{3} \cup \mathbb{N}\right)
$$

which maps the index of a node to the indices of its variable, lowand high-successor.

$$
u \mapsto(v, \ell, h)
$$

Note that 0 and 1 do not have a low- and high-successor. These external vertices are assigned a variable index which is $n+1$, where $n$ is the number of variables. (This choice simplifies some of the algorithms to be discussed later.)

## Operations on node table

$\operatorname{init}(T)$ : initializes $T$ to contain only nodes 0 and 1.

| $u$ | $\operatorname{var}(u)$ | $\operatorname{low}(u)$ | $\operatorname{high}(u)$ |
| :---: | :--- | :--- | :--- |
| 0 | $n+1$ |  |  |
| 1 | $n+1$ |  |  |

## Operations on node table

$u \leftarrow \operatorname{add}(T, i, \ell, h):$ allocate a new node $u$ with attributes $(i, \ell, h)$.

## Question

Given the node table

| $u$ | $\operatorname{var}(u)$ | $\operatorname{low}(u)$ | $\operatorname{high}(u)$ |
| :--- | :--- | :--- | :--- |
| 0 | $n+1$ |  |  |
| 1 | $n+1$ |  |  |

what does the operation $\operatorname{add}(T, 4,1,0)$ return?

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## Answer

2. 

## Operations on node table

$u \leftarrow \operatorname{add}(T, i, \ell, h):$ allocate a new node $u$ with attributes $(i, \ell, h)$.

## Question

Given the operation $\operatorname{add}(T, 4,1,0)$ applied to the node table

| $u$ | $\operatorname{var}(u)$ | $\operatorname{low}(u)$ | $\operatorname{high}(u)$ |
| :--- | :--- | :--- | :--- |
| 0 | 5 |  |  |
| 1 | 5 |  |  |

what is the resulting node table?

## Operations on node table

$u \leftarrow \operatorname{add}(T, i, \ell, h):$ allocate a new node $u$ with attributes $(i, \ell, h)$.

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| :--- | :--- | :--- | :--- |
| 0 | 5 |  |  |
| 1 | 5 |  |  |

what is the resulting node table?

## Answer

| $u$ | $\operatorname{var}(u)$ | $\operatorname{low}(u)$ | $\operatorname{high}(u)$ |
| :--- | :--- | :--- | :--- |
| 0 | 5 |  |  |
| 1 | 5 |  |  |
| 2 | 4 | 1 | 0 |

## Operations on node table

$\operatorname{var}(u)$ : look up the var attribute of $u$ in $T$
$\operatorname{low}(u)$ : look up the low attribute of $u$ in $T$ high(u) : look up the high attribute of $u$ in $T$

## Example of node table

## Question

Give the node table corresponding to the BDD


## Example of node table

## Answer

| $u$ | $\operatorname{var}(u)$ | $\operatorname{low}(u)$ | $\operatorname{high}(u)$ |
| :--- | :--- | :--- | :--- |
| 0 | 4 |  |  |
| 1 | 4 |  |  |
| 2 | 3 | 0 | 1 |
| 3 | 2 | 1 | 2 |
| 4 | 1 | 0 | 3 |

## Inverse of node table

The inverse of the node table can be viewed as a partial function

$$
H: \mathbb{N}^{3} \rightarrow \mathbb{N}
$$

which maps the indices of the attributes of a node to the index of the node.

$$
(v, \ell, h) \mapsto u
$$

For all $u \geq 2$,

$$
T(u)=(i, \ell, h) \text { iff } H(i, \ell, h)=u
$$

## Operations on inverse of node table

$$
\begin{aligned}
& \operatorname{init}(H): \\
& b \leftarrow \operatorname{member}(H, i, \ell, h): \\
& \text { check if }(i, \ell, h) \text { is in } H \\
& u \leftarrow \operatorname{lookup}(H, i, \ell, h): \quad \text { find } H(i, \ell, h) \\
& \operatorname{insert}(H, i, \ell, h, u): \quad \text { make }(i, \ell, h) \text { map to } u \text { in } H
\end{aligned}
$$

## Operations on BDDs

## Question

Consider the node table $T$ and its inverse $H$.

- Let $\ell$ and $h$ be indices of nodes $u_{\ell}$ and $u_{h}$.
- Let $i$ be the index of variable $x_{i}$. ${ }^{a}$

Return the index of the node of $T$ corresponding to $x_{i} \rightarrow u_{h}, u_{\ell}$ and expand $T$ and $H$ if needed.

[^0]
## Operations on BDDs

Мк[T, $H](i, \ell, h)$
if $\ell=h$ then
return $\ell$
else if member $(H, i, \ell, h)$ then
return lookup( $H, i, \ell, h$ )
else
$u \leftarrow \operatorname{add}(T, i, \ell, h)$
insert( $H, i, \ell, h)$
return $u$

## Operations on BDDs

## Question <br> Consider the node table $T$ and its inverse $H$. Let $t$ be a Boolean expression. Return the node of $T$ corresponding to $t$.

## Operations on BDDs

$\operatorname{Build}[T, H](t)$ return build $(t, 1)$
function build $(t, i)$
if $i>n$ then
if $t$ is false then return 0 else return 1 else

$$
\begin{aligned}
& u_{0} \leftarrow\left(t\left[0 / x_{i}\right], i+1\right) \\
& u_{1} \leftarrow\left(t\left[1 / x_{i}\right], i+1\right) \\
& \text { return } \operatorname{MK}\left(i, u_{0}, u_{1}\right)
\end{aligned}
$$

## Operations on BDDs

## Proposition

For all Boolean binary operators $\otimes$,

$$
\left(x \rightarrow t_{1}, t_{0}\right) \otimes\left(x \rightarrow u_{1}, u_{0}\right)=x \rightarrow t_{1} \otimes u_{1}, t_{0} \otimes u_{0}
$$

## Operations on BDDs

## Question

Consider the node table $T$ and its inverse $H$.

- Let $u_{1}$ and $u_{2}$ be indices of nodes.
- Let $\oplus$ be a Boolean binary operator.

Return the index of the node of $T$ corresponding to $u_{1} \oplus u_{2}$ and expand $T$ and $H$ if needed.

## Operations on BDDs

$\operatorname{Apply}[T, H]\left(\oplus, u_{1}, u_{2}\right)$
return $\operatorname{app}\left(u_{1}, u_{2}\right)$
function $\operatorname{app}\left(u_{1}, u_{2}\right)$
if $u_{1} \in\{0,1\}$ and $u_{1} \in\{0,1\}$ then

$$
u \leftarrow u_{1} \oplus u_{2}
$$

else if $\operatorname{var}\left(u_{1}\right)=\operatorname{var}\left(u_{2}\right)$ then
$u \leftarrow \operatorname{MK}\left(\operatorname{var}\left(u_{1}\right), \operatorname{app}\left(\operatorname{low}\left(u_{1}\right), \operatorname{low}\left(u_{2}\right)\right), \operatorname{app}\left(\operatorname{high}\left(u_{1}\right), \operatorname{high}\left(u_{2}\right)\right)\right.$ else if $\operatorname{var}\left(u_{1}\right)<\operatorname{var}\left(u_{2}\right)$ then

$$
u \leftarrow \operatorname{MK}\left(\operatorname{var}\left(u_{1}\right), \operatorname{app}\left(\operatorname{low}\left(u_{1}\right), u_{2}\right), \operatorname{app}\left(\operatorname{high}\left(u_{1}\right), u_{2}\right)\right)
$$

else

$$
u \leftarrow \operatorname{Mk}\left(\operatorname{var}\left(u_{2}\right), \operatorname{app}\left(u_{1}, \operatorname{low}\left(u_{2}\right)\right), \operatorname{app}\left(u_{1}, \operatorname{high}\left(u_{2}\right)\right)\right)
$$

return $u$

## Operations on BDDs

$\operatorname{Apply}[T, H]\left(\oplus, u_{1}, u_{2}\right)$ $\operatorname{init}(G)$
return $\operatorname{app}\left(u_{1}, u_{2}\right)$
function $\operatorname{app}\left(u_{1}, u_{2}\right)$
if $G\left(u_{1}, u_{2}\right) \neq$ empty then return $G\left(u_{1}, u_{2}\right)$
if $u_{1} \in\{0,1\}$ and $u_{1} \in\{0,1\}$ then

$$
u \leftarrow u_{1} \oplus u_{2}
$$

else if $\operatorname{var}\left(u_{1}\right)=\operatorname{var}\left(u_{2}\right)$ then

$$
u \leftarrow \operatorname{Mk}\left(\operatorname{var}\left(u_{1}\right), \operatorname{app}\left(\operatorname{low}\left(u_{1}\right), \operatorname{low}\left(u_{2}\right)\right), \operatorname{app}\left(h i g h\left(u_{1}\right), \text { high }\left(u_{2}\right)\right)\right.
$$

else if $\operatorname{var}\left(u_{1}\right)<\operatorname{var}\left(u_{2}\right)$ then

$$
u \leftarrow \operatorname{MK}\left(\operatorname{var}\left(u_{1}\right), \operatorname{app}\left(\operatorname{low}\left(u_{1}\right), u_{2}\right), \operatorname{app}\left(\operatorname{high}\left(u_{1}\right), u_{2}\right)\right)
$$

else

$$
u \leftarrow \operatorname{MK}\left(\operatorname{var}\left(u_{2}\right), \operatorname{app}\left(u_{1}, \operatorname{low}\left(u_{2}\right)\right), \operatorname{app}\left(u_{1}, \operatorname{high}\left(u_{2}\right)\right)\right)
$$

$$
G\left(u_{1}, u_{2}\right) \leftarrow u
$$

return $u$


[^0]:    ${ }^{a}$ In the variable ordering, this variable occurs before all variables occurring in the subgraphs rooted at $\ell$ and $h$.

